

Computational Intelligence

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Three tasks:

1. Choice of an appropriate problem representation.
2. Choice / design of variation operators acting in problem representation.
3. Choice of strategy parameters (includes initialization).

ad 1) different "schools":

- (a) operate on binary representation and define genotype/phenotype mapping
 - + can use standard algorithm
 - mapping may induce unintentional bias in search
- (b) no doctrine: use "most natural" representation
 - must design variation operators for specific representation
 - + if design done properly then no bias in search

ad 2) design guidelines for variation operators

a) *reachability*

every $x \in X$ should be reachable from arbitrary $x_0 \in X$
after finite number of repeated variations with positive probability bounded from 0

b) *unbiasedness*

unless having gathered knowledge about problem
variation operator should not favor particular subsets of solutions
⇒ formally: maximum entropy principle

c) *control*

variation operator should have parameters affecting shape of distributions;
known from theory: weaken variation strength when approaching optimum

ad 2) design guidelines for variation operators **in practice**

binary search space $X = \mathbb{B}^n$

variation by k-point or uniform crossover and subsequent mutation

a) *reachability*:

regardless of the output of crossover
we can move from $x \in \mathbb{B}^n$ to $y \in \mathbb{B}^n$ in 1 step with probability

$$p(x, y) = p_m^{H(x,y)} (1 - p_m)^{n-H(x,y)} > 0$$

where $H(x,y)$ is Hamming distance between x and y .

Since $\min\{p(x,y): x,y \in \mathbb{B}^n\} = \delta > 0$ we are done.

b) *unbiasedness*

don't prefer any direction or subset of points without reason

⇒ use maximum entropy distribution for sampling!

properties:

- distributes probability mass as uniform as possible
- additional knowledge can be included as constraints:
→ under given constraints sample as uniform as possible

Formally:**Definition:**

Let X be discrete random variable (r.v.) with $p_k = P\{X = x_k\}$ for some index set K . The quantity

$$H(X) = - \sum_{k \in K} p_k \log p_k$$

is called the **entropy of the distribution** of X . If X is a continuous r.v. with p.d.f. $f_X(\cdot)$ then the entropy is given by

$$H(X) = - \int_{-\infty}^{\infty} f_X(x) \log f_X(x) dx$$

The distribution of a random variable X for which $H(X)$ is maximal is termed a **maximum entropy distribution**. ■

Excursion: Maximum Entropy Distributions

Lecture 11

Knowledge available:

Discrete distribution with support $\{x_1, x_2, \dots, x_n\}$ with $x_1 < x_2 < \dots < x_n < \infty$

$$p_k = P\{X = x_k\}$$

⇒ leads to nonlinear constrained optimization problem:

$$\begin{aligned} - \sum_{k=1}^n p_k \log p_k &\rightarrow \max! \\ \text{s.t. } \sum_{k=1}^n p_k &= 1 \end{aligned}$$

solution: via Lagrange (find stationary point of Lagrangian function)

$$L(p, a) = - \sum_{k=1}^n p_k \log p_k + a \left(\sum_{k=1}^n p_k - 1 \right)$$

Excursion: Maximum Entropy Distributions

Lecture 11

$$L(p, a) = - \sum_{k=1}^n p_k \log p_k + a \left(\sum_{k=1}^n p_k - 1 \right)$$

partial derivatives:

$$\begin{aligned} \frac{\partial L(p, a)}{\partial p_k} &= -1 - \log p_k + a \stackrel{!}{=} 0 && \Rightarrow p_k \stackrel{!}{=} e^{a-1} \\ \frac{\partial L(p, a)}{\partial a} &= \sum_{k=1}^n p_k - 1 \stackrel{!}{=} 0 && \left. \begin{array}{l} \text{uniform} \\ \text{distribution} \end{array} \right\} p_k = \frac{1}{n} \end{aligned}$$

$$\Rightarrow \sum_{k=1}^n p_k = \sum_{k=1}^n e^{a-1} = n e^{a-1} \stackrel{!}{=} 1 \Leftrightarrow e^{a-1} = \frac{1}{n}$$

Knowledge available:

Discrete distribution with support $\{1, 2, \dots, n\}$ with $p_k = P\{X = k\}$ and $E[X] = \nu$

⇒ leads to nonlinear constrained optimization problem:

$$-\sum_{k=1}^n p_k \log p_k \rightarrow \max!$$

$$\text{s.t.} \quad \sum_{k=1}^n p_k = 1 \quad \text{and} \quad \sum_{k=1}^n k p_k = \nu$$

solution: via Lagrange (find stationary point of Lagrangian function)

$$L(p, a, b) = -\sum_{k=1}^n p_k \log p_k + a \left(\sum_{k=1}^n p_k - 1 \right) + b \left(\sum_{k=1}^n k \cdot p_k - \nu \right)$$

$$L(p, a, b) = -\sum_{k=1}^n p_k \log p_k + a \left(\sum_{k=1}^n p_k - 1 \right) + b \left(\sum_{k=1}^n k \cdot p_k - \nu \right)$$

partial derivatives:

$$\frac{\partial L(p, a, b)}{\partial p_k} = -1 - \log p_k + a + b k \stackrel{!}{=} 0 \quad \Rightarrow \quad p_k = e^{a-1+bk}$$

$$\frac{\partial L(p, a, b)}{\partial a} = \sum_{k=1}^n p_k - 1 \stackrel{!}{=} 0$$

$$\frac{\partial L(p, a, b)}{\partial b} = \sum_{k=1}^n k p_k - \nu \stackrel{!}{=} 0 \quad \Rightarrow \quad \sum_{k=1}^n p_k = e^{a-1} \sum_{k=1}^n (e^b)^k \stackrel{!}{=} 1$$

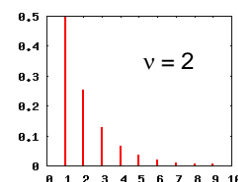
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$$\Rightarrow e^{a-1} = \frac{1}{\sum_{k=1}^n (e^b)^k} \quad \Rightarrow \quad p_k = e^{a-1+bk} = \frac{(e^b)^k}{\sum_{i=1}^n (e^b)^i}$$

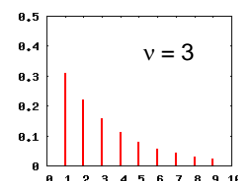
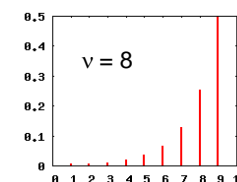
$$\Rightarrow \text{discrete Boltzmann distribution} \quad p_k = \frac{q^k}{\sum_{i=1}^n q^i} \quad (q = e^b)$$

⇒ value of q depends on ν via third condition: (*)

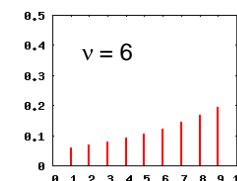
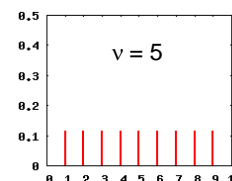
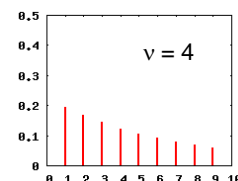
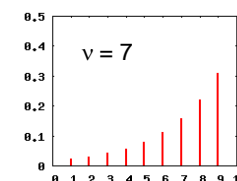
$$\sum_{k=1}^n k p_k = \frac{\sum_{k=1}^n k q^k}{\sum_{i=1}^n q^i} = \frac{1 - (n+1)q^n + nq^{n+1}}{(1-q)(1-q^n)} \stackrel{!}{=} \nu$$



Boltzmann distribution
($n = 9$)



specializes to uniform
distribution if $\nu = 5$
(as expected)



Knowledge available:

Discrete distribution with support $\{1, 2, \dots, n\}$ with $E[X] = \nu$ and $V[X] = \eta^2$

⇒ leads to nonlinear constrained optimization problem:

$$-\sum_{k=1}^n p_k \log p_k \rightarrow \max!$$

$$\text{s.t. } \sum_{k=1}^n p_k = 1 \quad \text{and} \quad \sum_{k=1}^n k p_k = \nu \quad \text{and} \quad \sum_{k=1}^n (k - \nu)^2 p_k = \eta^2$$

solution: in principle, via Lagrange (find stationary point of Lagrangian function)

but very complicated analytically, if possible at all

⇒ consider special cases only

note: constraints are linear equations in p_k

Special case: $n = 3$ and $E[X] = 2$ and $V[X] = \eta^2$

Linear constraints uniquely determine distribution:

$$\text{I. } p_1 + p_2 + p_3 = 1$$

$$\text{II. } p_1 + 2p_2 + 3p_3 = 2$$

$$\text{III. } p_1 + 0 + p_3 = \eta^2$$

$$\text{II-I: } p_2 + 2p_3 = 1$$

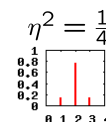
$$\text{I-III: } p_2 = 1 - \eta^2$$

$$p_1 = \frac{\eta^2}{2}$$

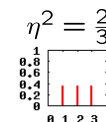
↑ insertion in III.

$$p_3 = \frac{\eta^2}{2}$$

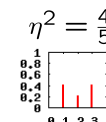
$$\Rightarrow p = \left(\frac{\eta^2}{2}, 1 - \eta^2, \frac{\eta^2}{2} \right)$$



unimodal



uniform



bimodal

Knowledge available:

Discrete distribution with unbounded support $\{0, 1, 2, \dots\}$ and $E[X] = \nu$

⇒ leads to infinite-dimensional nonlinear constrained optimization problem:

$$-\sum_{k=0}^{\infty} p_k \log p_k \rightarrow \max!$$

$$\text{s.t. } \sum_{k=0}^{\infty} p_k = 1 \quad \text{and} \quad \sum_{k=0}^{\infty} k p_k = \nu$$

solution: via Lagrange (find stationary point of Lagrangian function)

$$L(p, a, b) = -\sum_{k=0}^{\infty} p_k \log p_k + a \left(\sum_{k=0}^{\infty} p_k - 1 \right) + b \left(\sum_{k=0}^{\infty} k \cdot p_k - \nu \right)$$

$$L(p, a, b) = -\sum_{k=0}^{\infty} p_k \log p_k + a \left(\sum_{k=0}^{\infty} p_k - 1 \right) + b \left(\sum_{k=0}^{\infty} k \cdot p_k - \nu \right)$$

partial derivatives:

$$\frac{\partial L(p, a, b)}{\partial p_k} = -1 - \log p_k + a + b k \stackrel{!}{=} 0 \quad \Rightarrow p_k = e^{a-1+bk}$$

$$\frac{\partial L(p, a, b)}{\partial a} = \sum_{k=0}^{\infty} p_k - 1 \stackrel{!}{=} 0$$

$$\frac{\partial L(p, a, b)}{\partial b} \stackrel{(*)}{=} \sum_{k=0}^{\infty} k p_k - \nu \stackrel{!}{=} 0 \quad \Leftrightarrow \sum_{k=0}^{\infty} p_k = e^{a-1} \sum_{k=0}^{\infty} (e^b)^k \stackrel{!}{=} 1$$

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$$\Rightarrow e^{a-1} = \frac{1}{\sum_{k=0}^{\infty} (e^b)^k} \quad \Rightarrow p_k = e^{a-1+bk} = \frac{(e^b)^k}{\sum_{i=0}^{\infty} (e^b)^i}$$

set $q = e^b$ and insists that $q < 1 \Rightarrow \sum_{k=0}^{\infty} q^k = \frac{1}{1-q}$ insert

$$\Rightarrow p_k = (1-q)q^k \quad \text{for } k = 0, 1, 2, \dots \quad \text{geometrical distribution}$$

it remains to specify q ; to proceed recall that $\sum_{k=0}^{\infty} k q^k = \frac{q}{(1-q)^2}$

\Rightarrow value of q depends on ν via third condition: ($*$)

$$\sum_{k=0}^{\infty} k p_k = \frac{\sum_{k=0}^{\infty} k q^k}{\sum_{i=0}^{\infty} q^i} = \frac{q}{1-q} \stackrel{!}{=} \nu$$

$$\Rightarrow q = \frac{\nu}{\nu+1} = 1 - \frac{1}{\nu+1}$$

$$\Rightarrow p_k = \frac{1}{\nu+1} \left(1 - \frac{1}{\nu+1}\right)^k$$

geometrical distribution

with $E[x] = \nu$

p_k only shown
for $k = 0, 1, \dots, 8$

