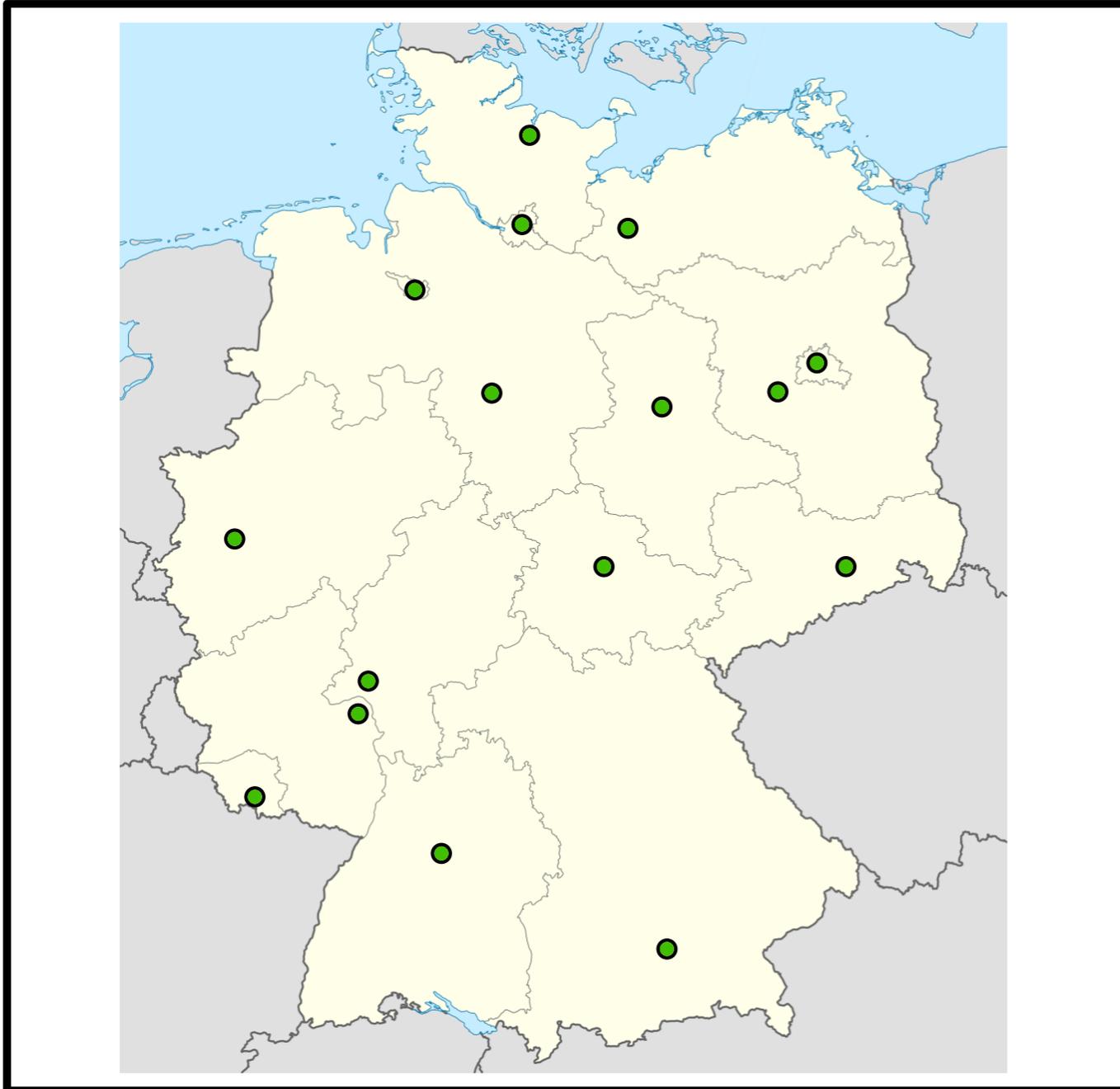


Quadtrees

Geometric Approximation Algorithms

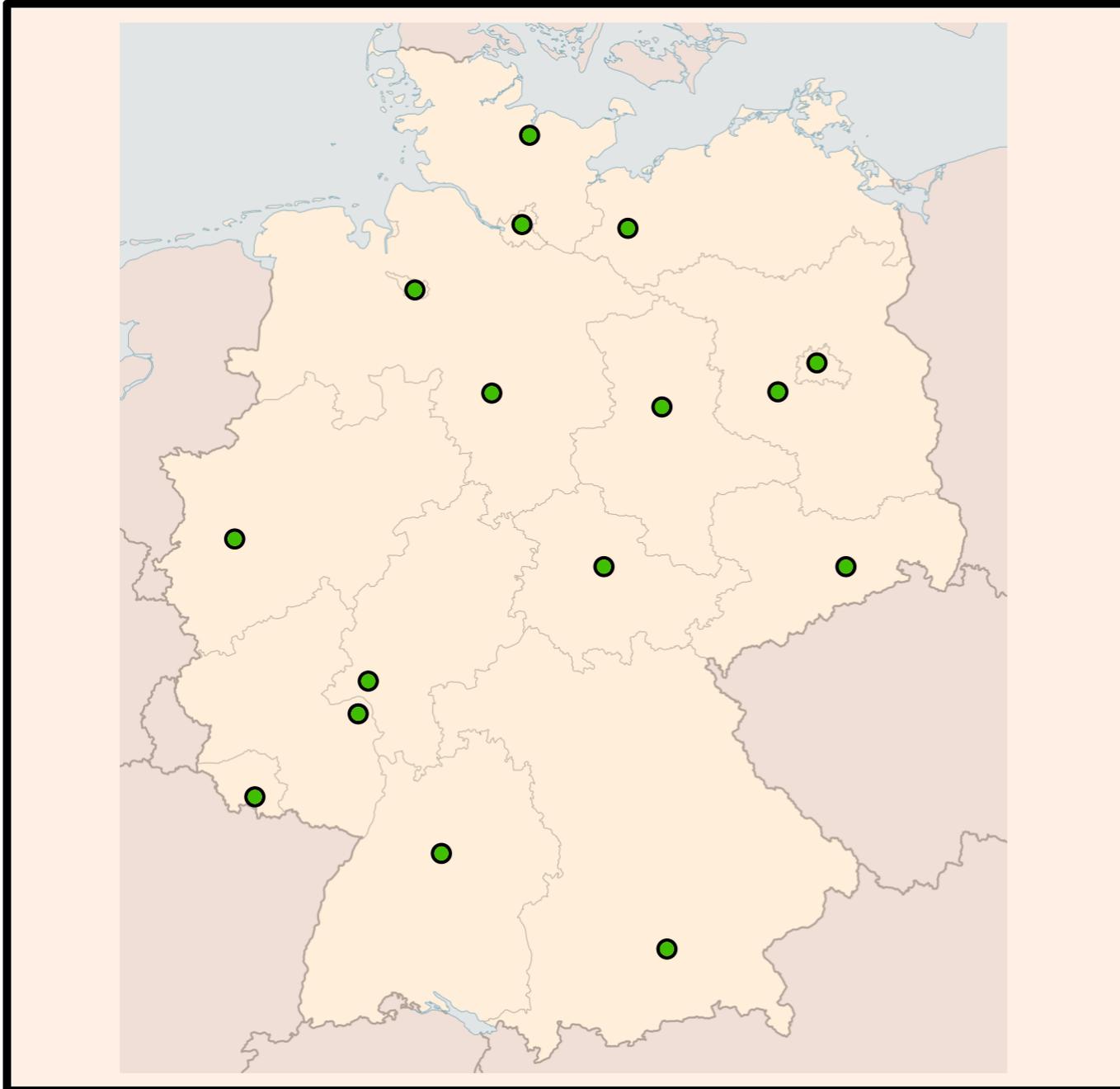
Quadtrees: a simple point-location data structure



Main idea: Use a **tree structure** to be able to quickly find location of point

- nodes represent squares
- recursively subdivide squares into 4 until 1 point per square

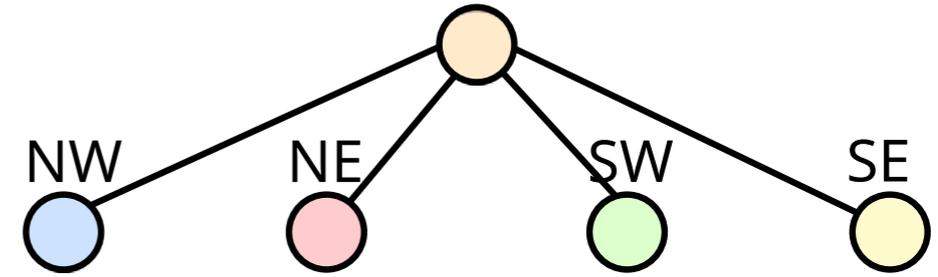
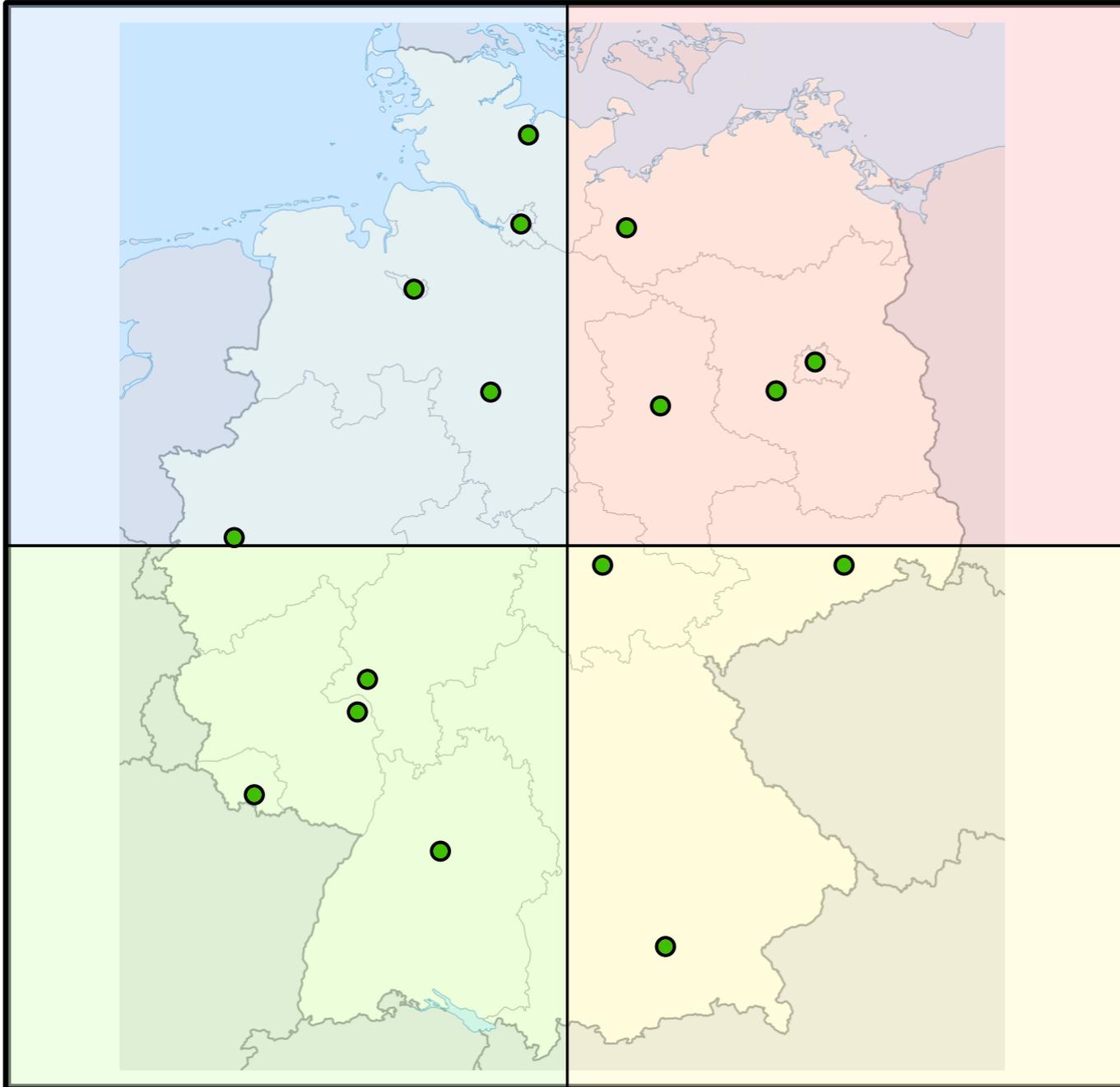
Quadtrees: a simple point-location data structure



Main idea: Use a **tree structure** to be able to quickly find location of point

- nodes represent squares
- recursively subdivide squares into 4 until 1 point per square

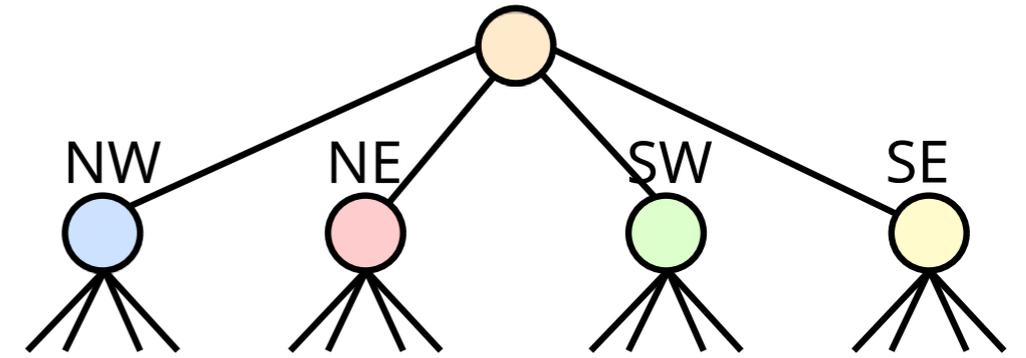
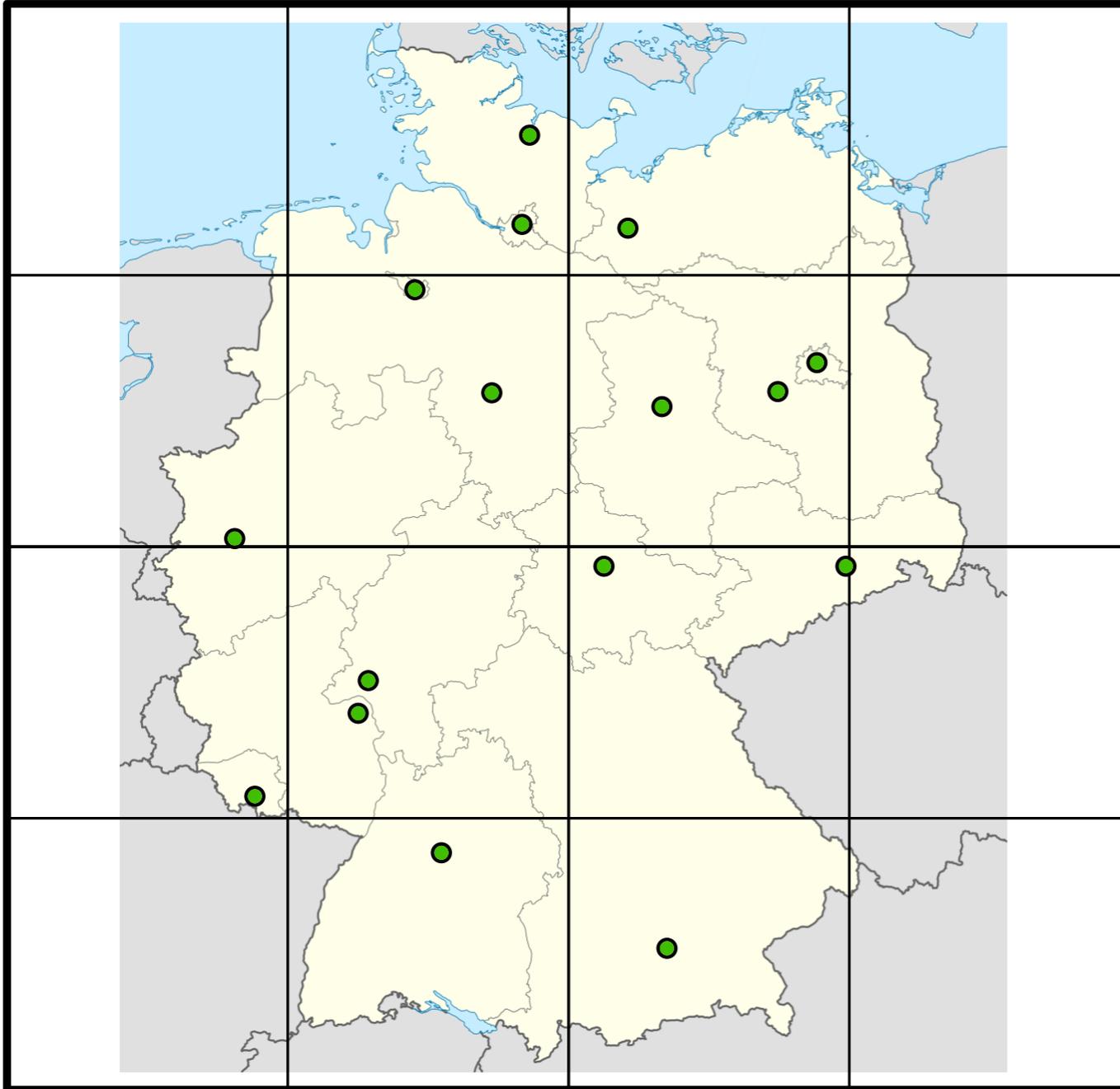
Quadtrees: a simple point-location data structure



Main idea: Use a **tree structure** to be able to quickly find location of point

- nodes represent squares
- recursively subdivide squares into 4 until 1 point per square

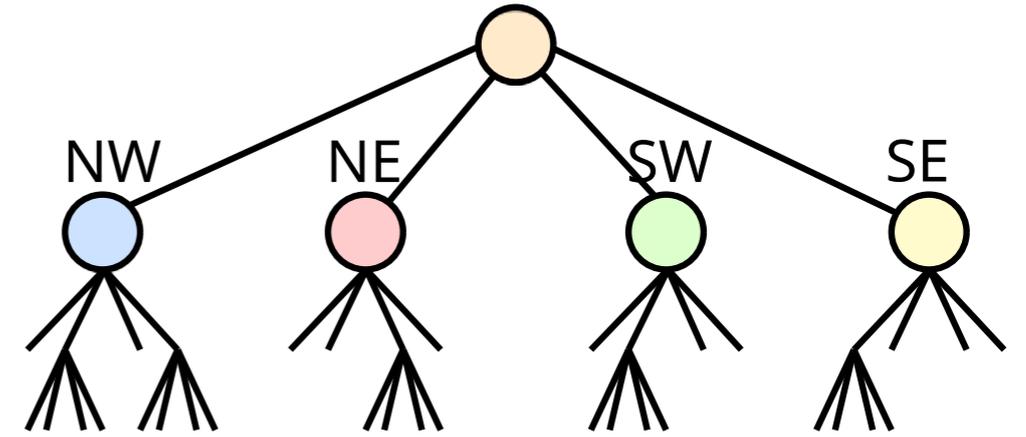
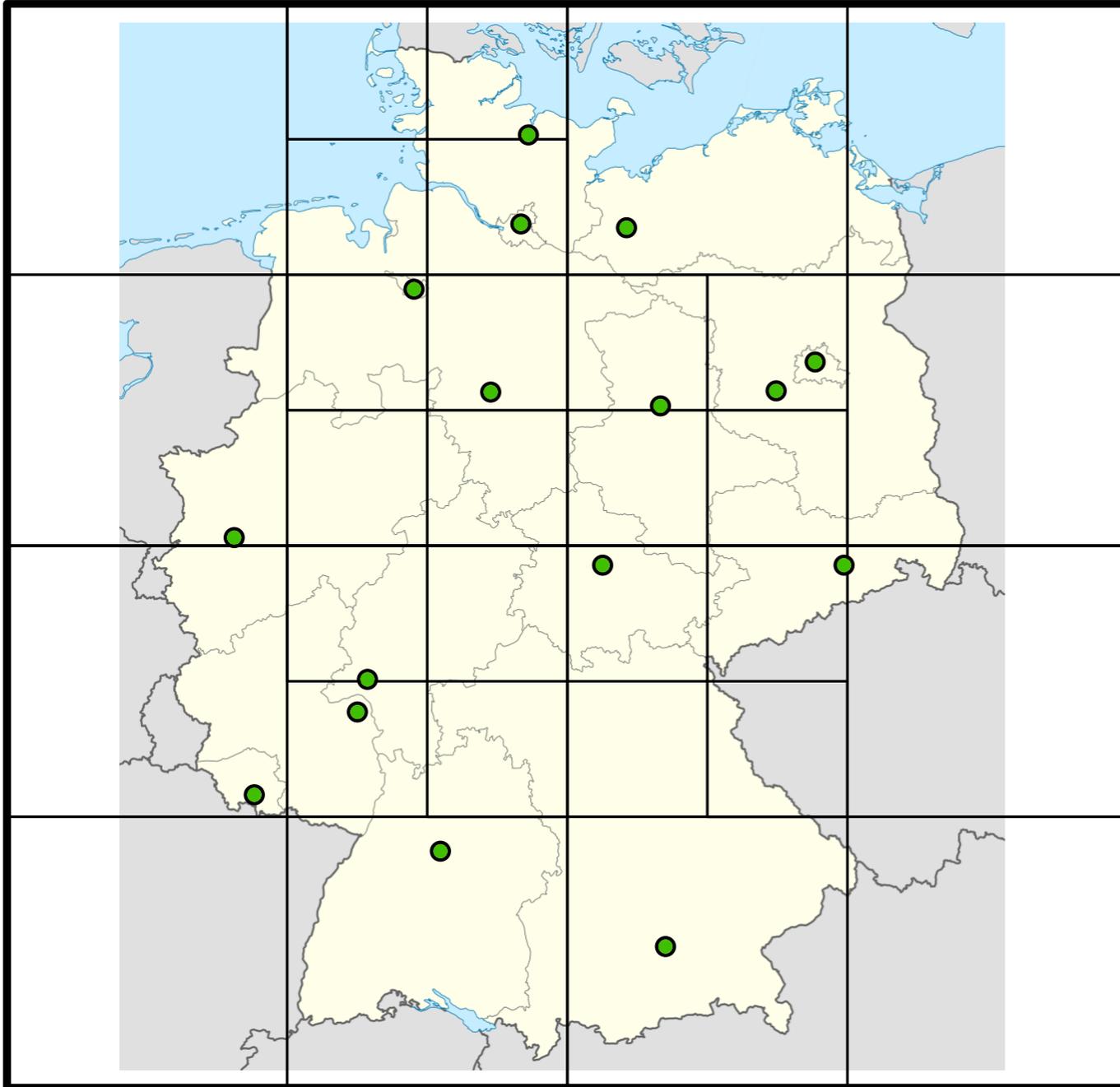
Quadtrees: a simple point-location data structure



Main idea: Use a **tree structure** to be able to quickly find location of point

- nodes represent squares
- recursively subdivide squares into 4 until 1 point per square

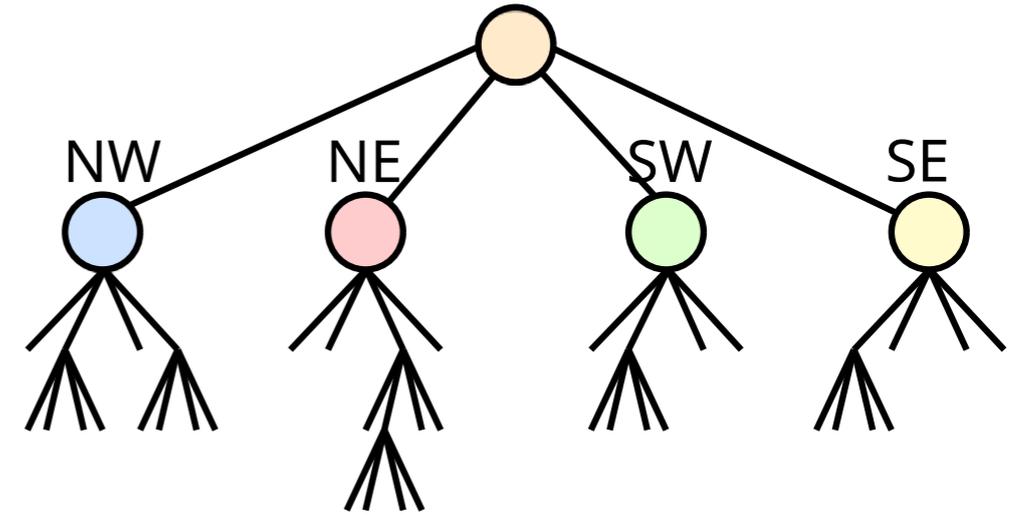
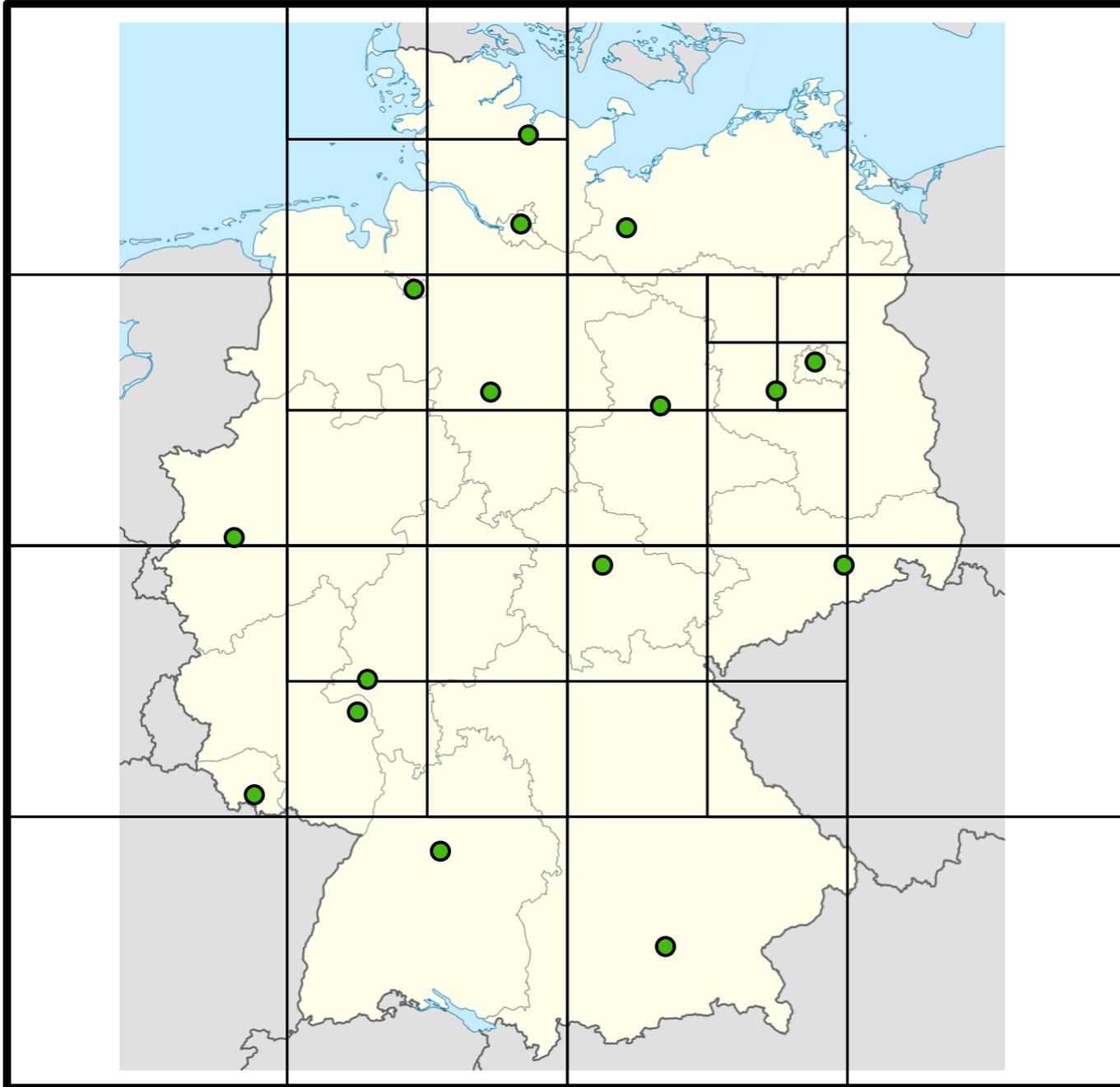
Quadtrees: a simple point-location data structure



Main idea: Use a **tree structure** to be able to quickly find location of point

- nodes represent squares
- recursively subdivide squares into 4 until 1 point per square

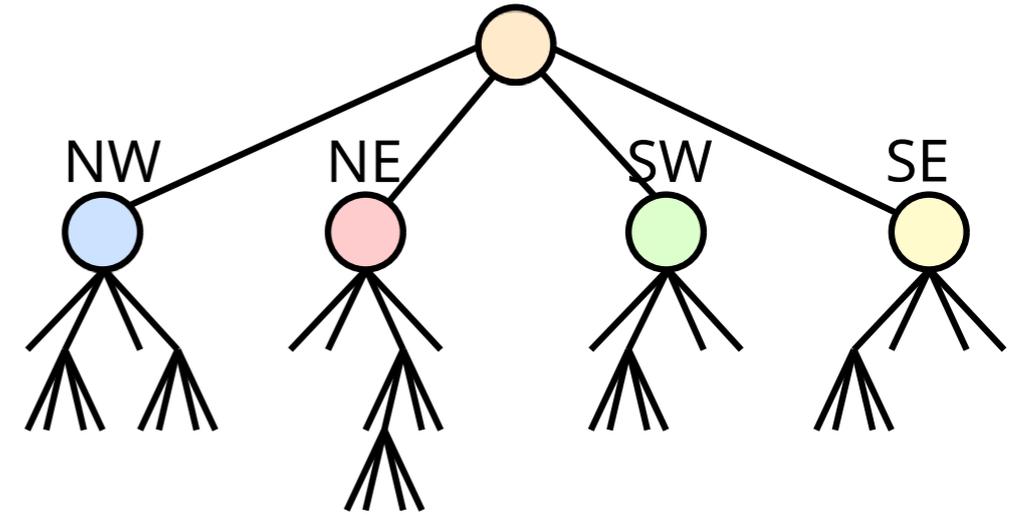
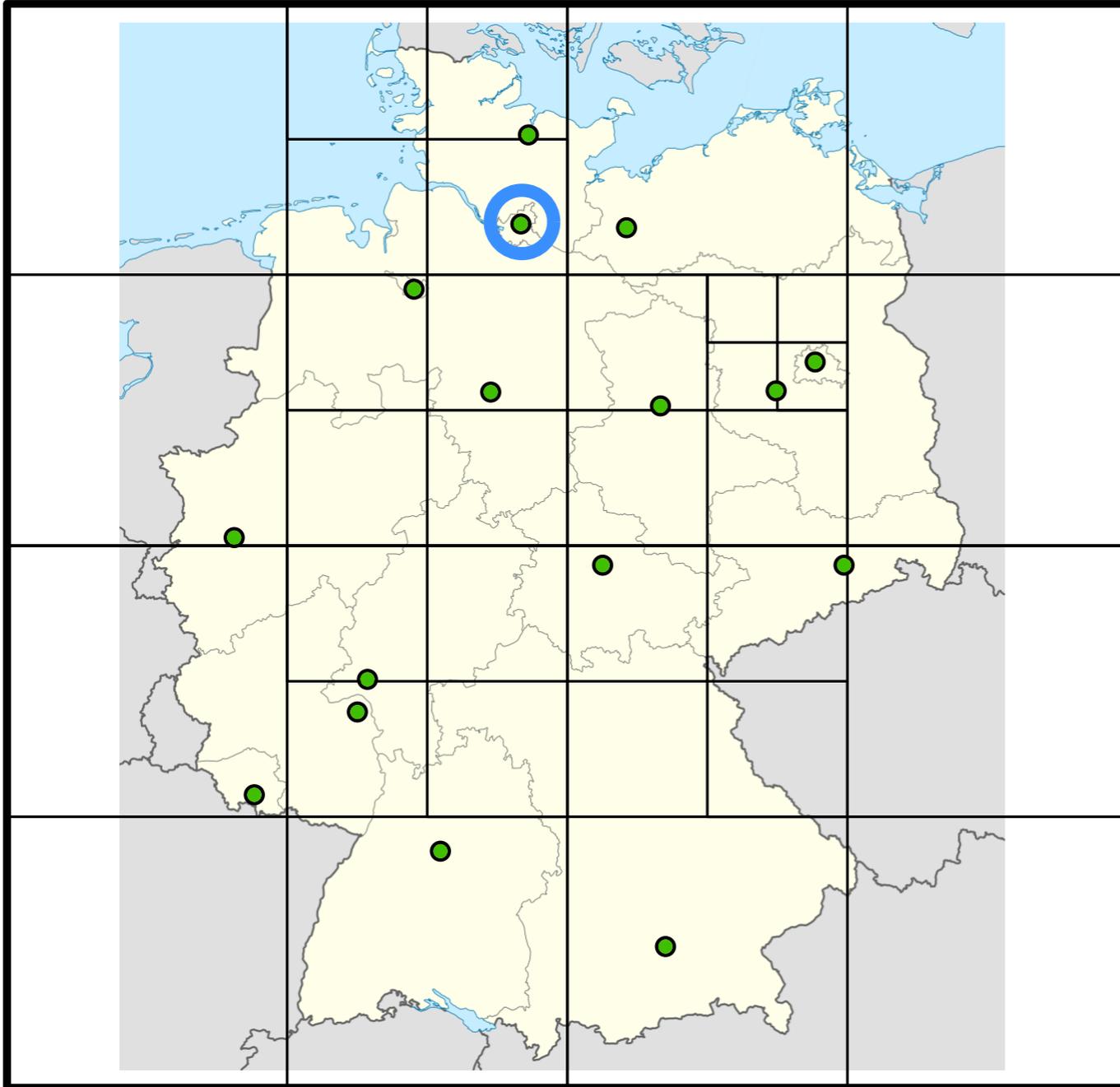
Quadtrees: a simple point-location data structure



Main idea: Use a **tree structure** to be able to quickly find location of point

- nodes represent squares
- recursively subdivide squares into 4 until 1 point per square

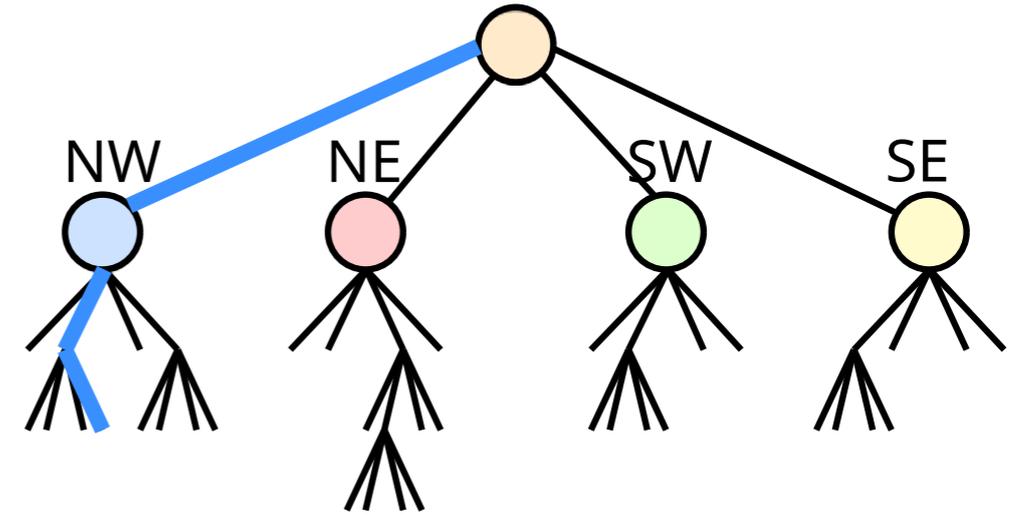
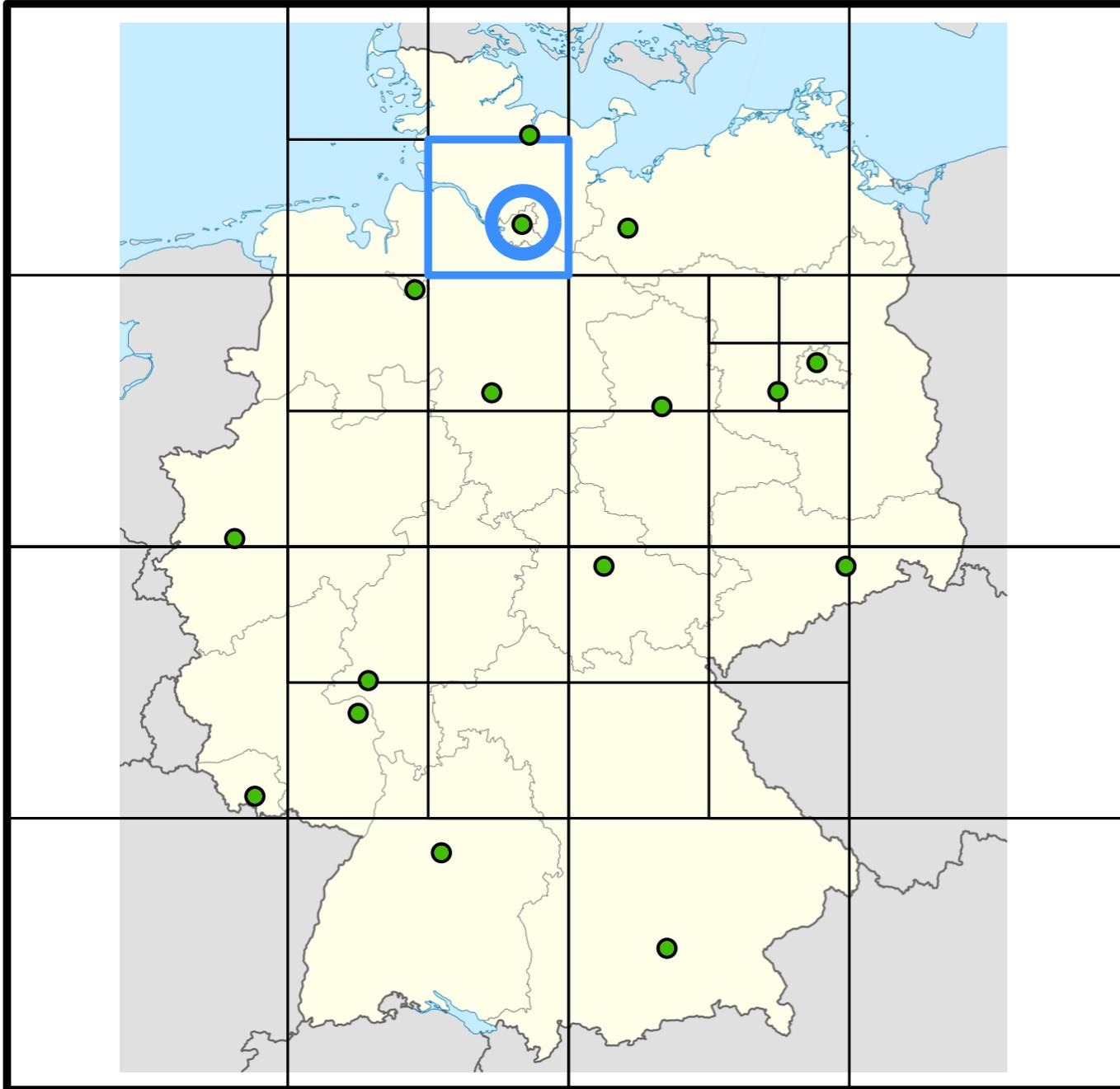
Quadtrees: a simple point-location data structure



Main idea: Use a **tree structure** to be able to quickly find location of point

- nodes represent squares
- recursively subdivide squares into 4 until 1 point per square

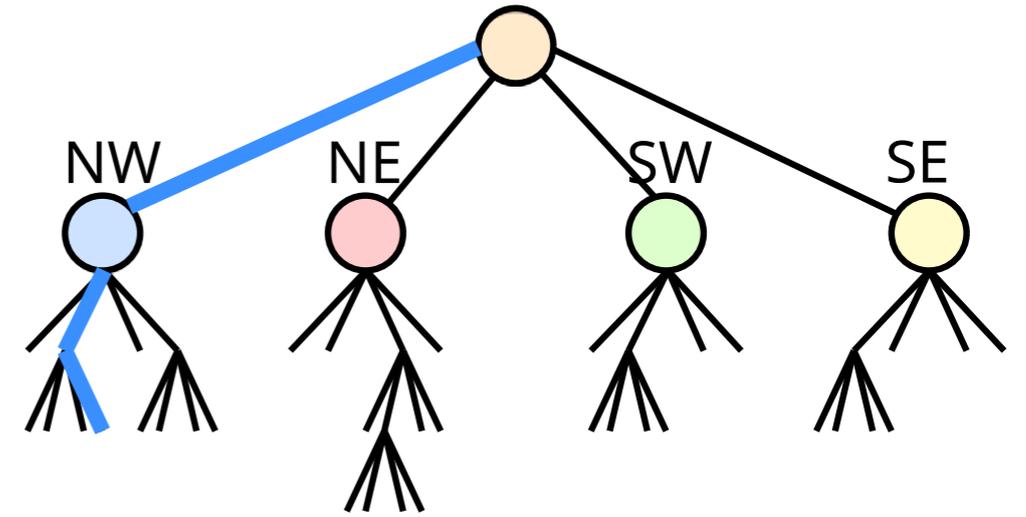
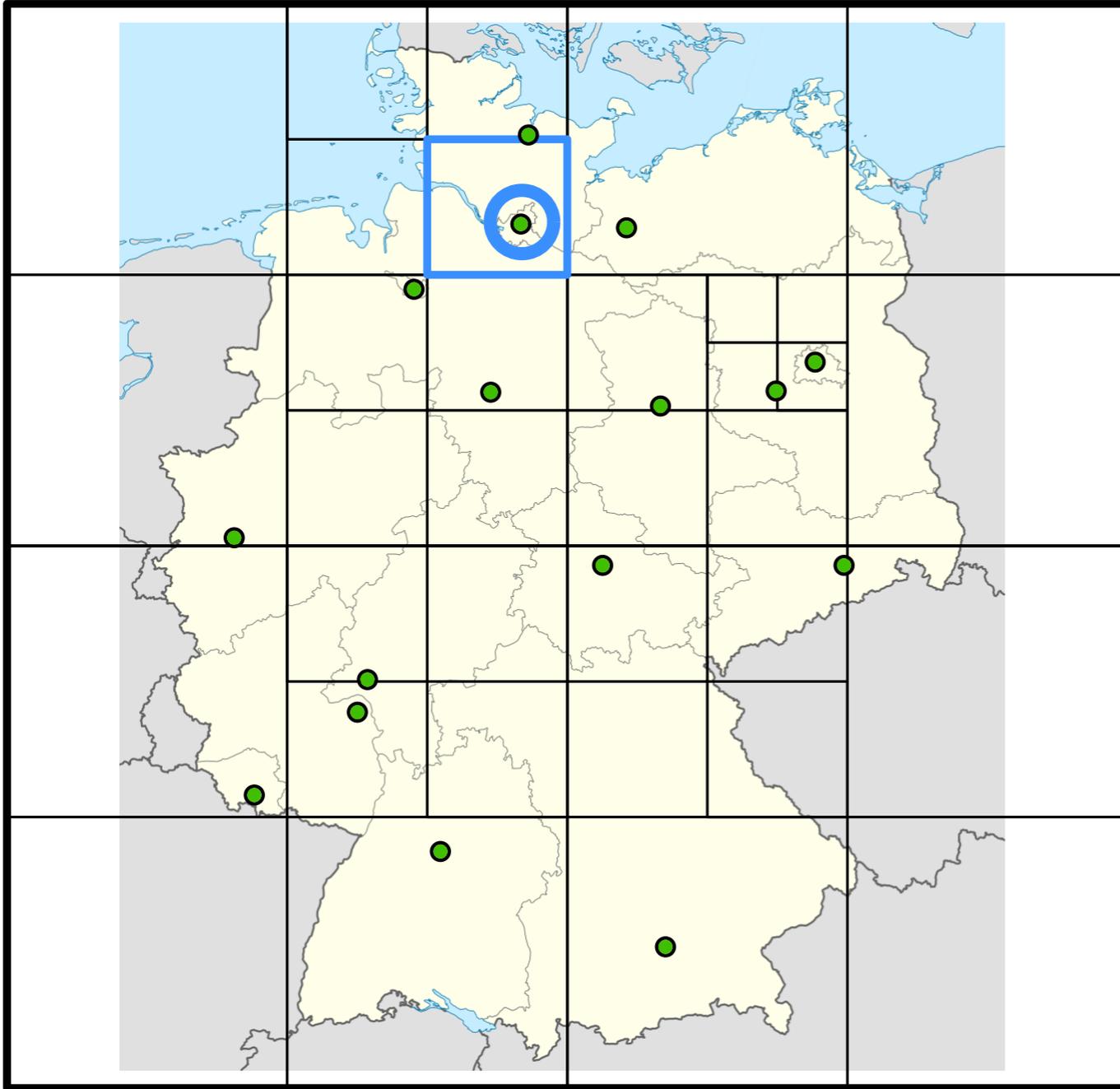
Quadtrees: a simple point-location data structure



Main idea: Use a **tree structure** to be able to quickly find location of point

- nodes represent squares
- recursively subdivide squares into 4 until 1 point per square

Quadtrees: a simple point-location data structure



Simple point location: $O(d)$

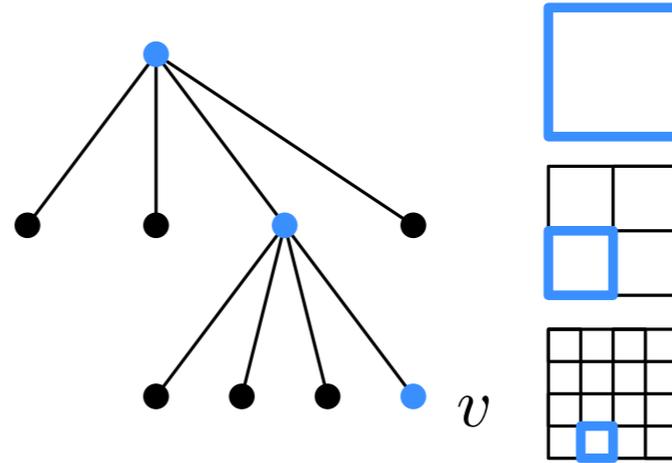
for n points and quadtree of depth d

(+ check regions overlapping with leaf square)

Quadtrees: multi-scale grids

node v at depth i :

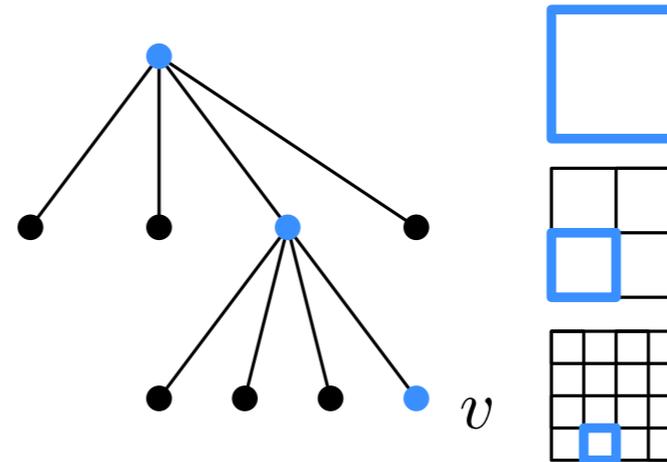
- square $S_v \rightarrow$ side length $= 2^{-i}$
- in grid $G_{2^{-i}}$
- level $\ell(v) = -i$
- $id(v) = (\ell(v), \lfloor x/2^{\ell(v)} \rfloor, \lfloor y/2^{\ell(v)} \rfloor)$,
with (x, y) a point in S_v



Quadtrees: multi-scale grids

node v at depth i :

- square $S_v \rightarrow$ side length = 2^{-i}
- in grid $G_{2^{-i}}$
- level $\ell(v) = -i$
- $id(v) = (\ell(v), \lfloor x/2^{\ell(v)} \rfloor, \lfloor y/2^{\ell(v)} \rfloor)$,
with (x, y) a point in S_v



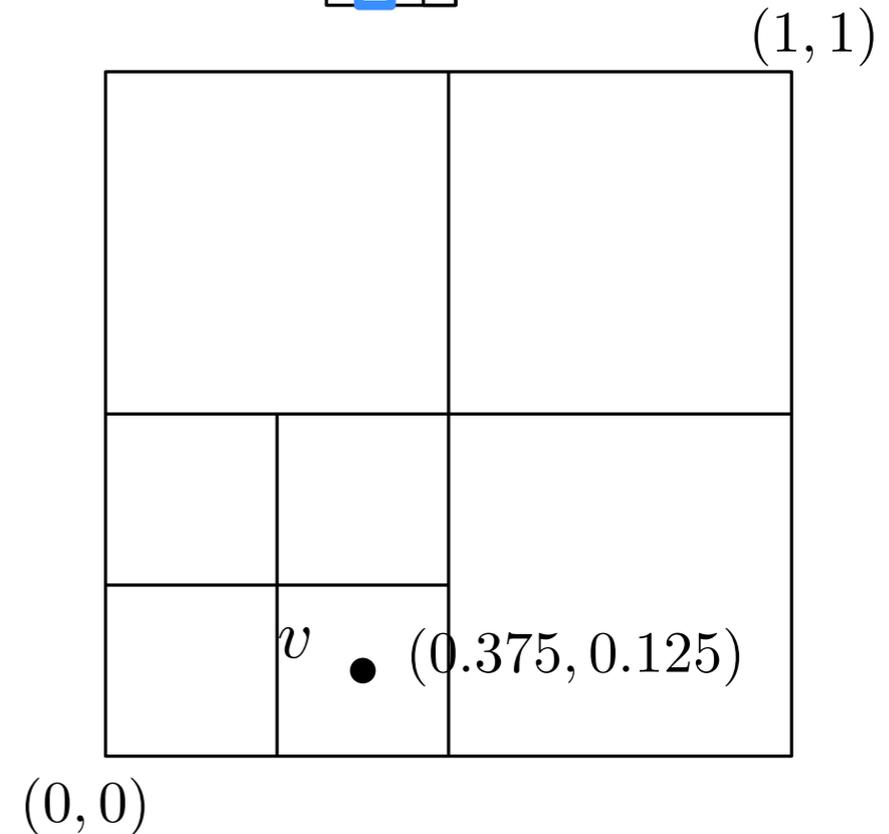
Quiz What is $id(v)$ in this example?

A (-1,2,1)

B (-1,3,4)

C (-2,2,2)

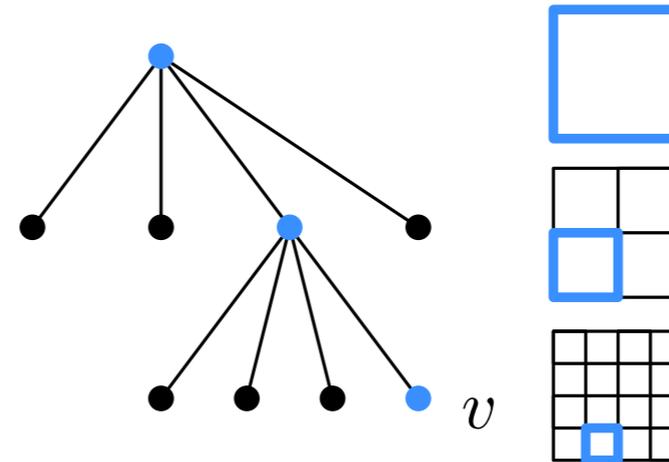
D (-2,1,0)



Quadrees: multi-scale grids

node v at depth i :

- square $S_v \rightarrow$ side length $= 2^{-i}$
- in grid $G_{2^{-i}}$
- level $\ell(v) = -i$
- $id(v) = (\ell(v), \lfloor x/2^{\ell(v)} \rfloor, \lfloor y/2^{\ell(v)} \rfloor)$,
with (x, y) a point in S_v



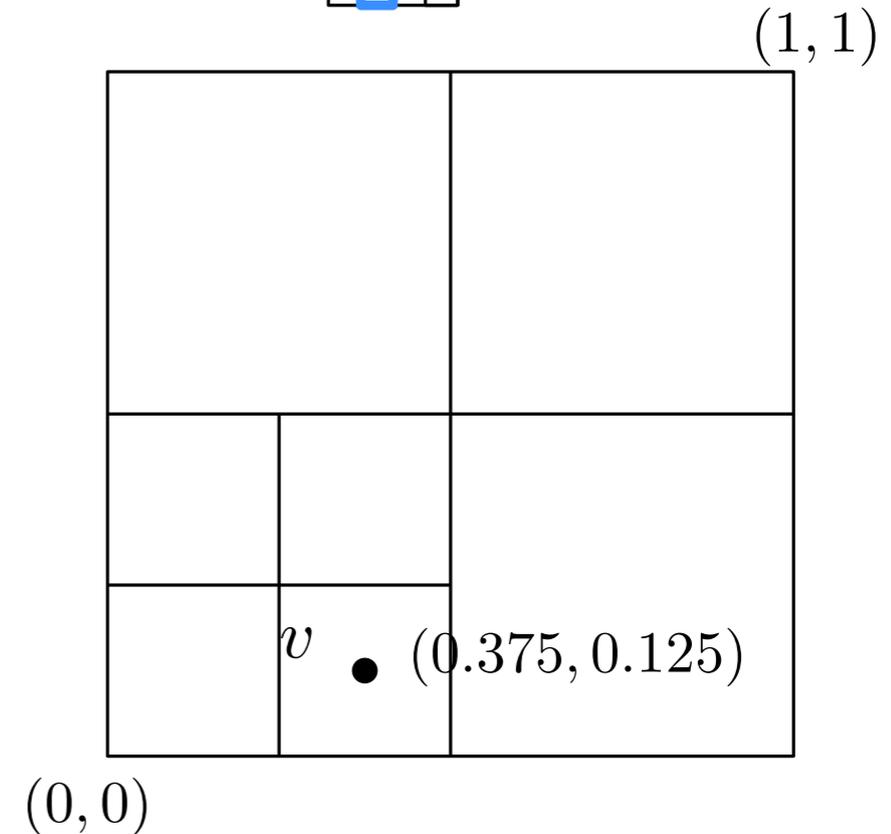
Quiz What is $id(v)$ in this example?

A (-1,2,1)

B (-1,3,4)

C (-2,2,2)

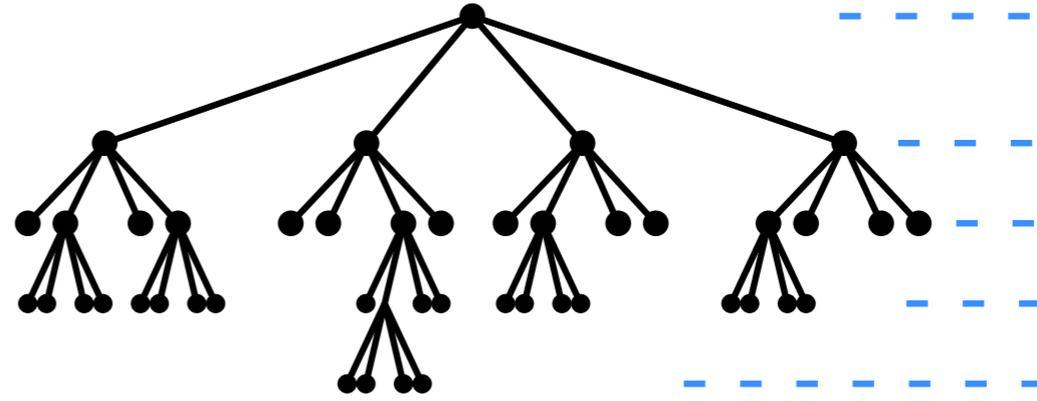
D (-2,1,0)



Quadtrees: multi-scale grids

node v at depth i :

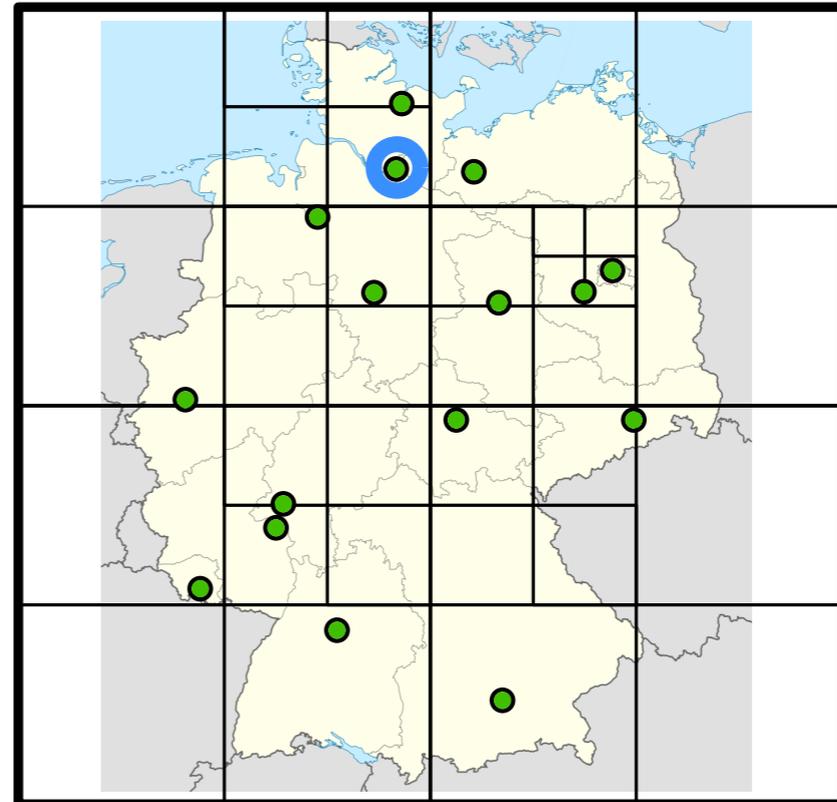
- square $S_v \rightarrow$ side length $= 2^{-i}$
- in grid $G_{2^{-i}}$
- level $\ell(v) = -i$
- $id(v) = (\ell(v), \lfloor x/2^{\ell(v)} \rfloor, \lfloor y/2^{\ell(v)} \rfloor)$,
with (x, y) a point in S_v



Faster point location:

preprocessing: build hash table using $id(v)$

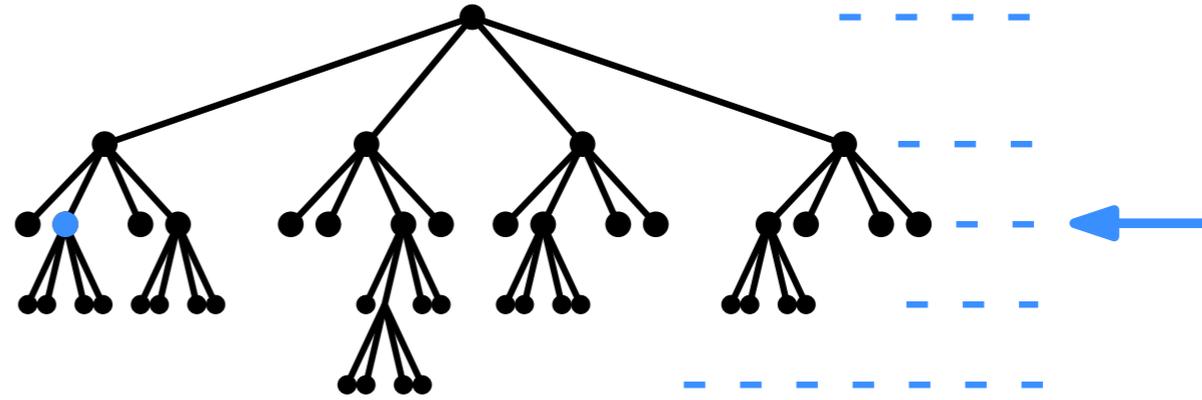
query: binary search on levels



Quadtrees: multi-scale grids

node v at depth i :

- square $S_v \rightarrow$ side length $= 2^{-i}$
- in grid $G_{2^{-i}}$
- level $\ell(v) = -i$
- $id(v) = (\ell(v), \lfloor x/2^{\ell(v)} \rfloor, \lfloor y/2^{\ell(v)} \rfloor)$,
with (x, y) a point in S_v

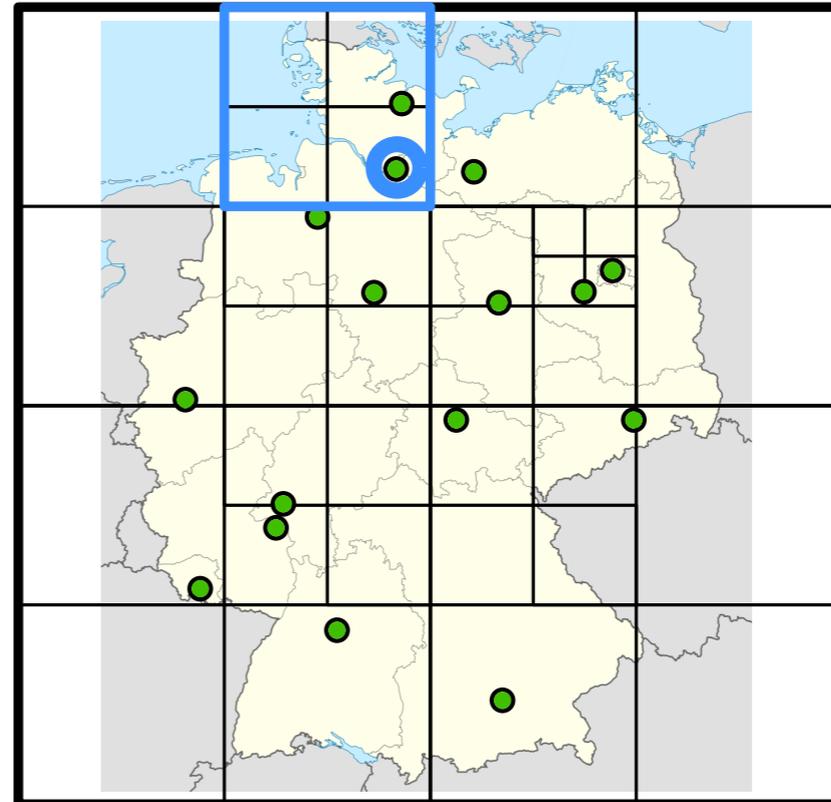


Faster point location:

preprocessing: build hash table using $id(v)$

query: binary search on levels

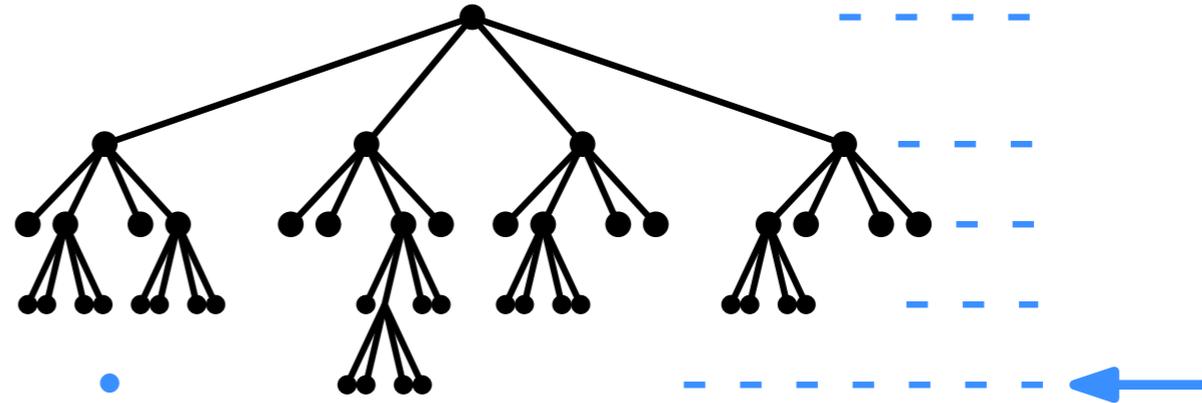
- if inner node: recurse in lower half



Quadtrees: multi-scale grids

node v at depth i :

- square $S_v \rightarrow$ side length $= 2^{-i}$
- in grid $G_{2^{-i}}$
- level $\ell(v) = -i$
- $id(v) = (\ell(v), \lfloor x/2^{\ell(v)} \rfloor, \lfloor y/2^{\ell(v)} \rfloor)$,
with (x, y) a point in S_v

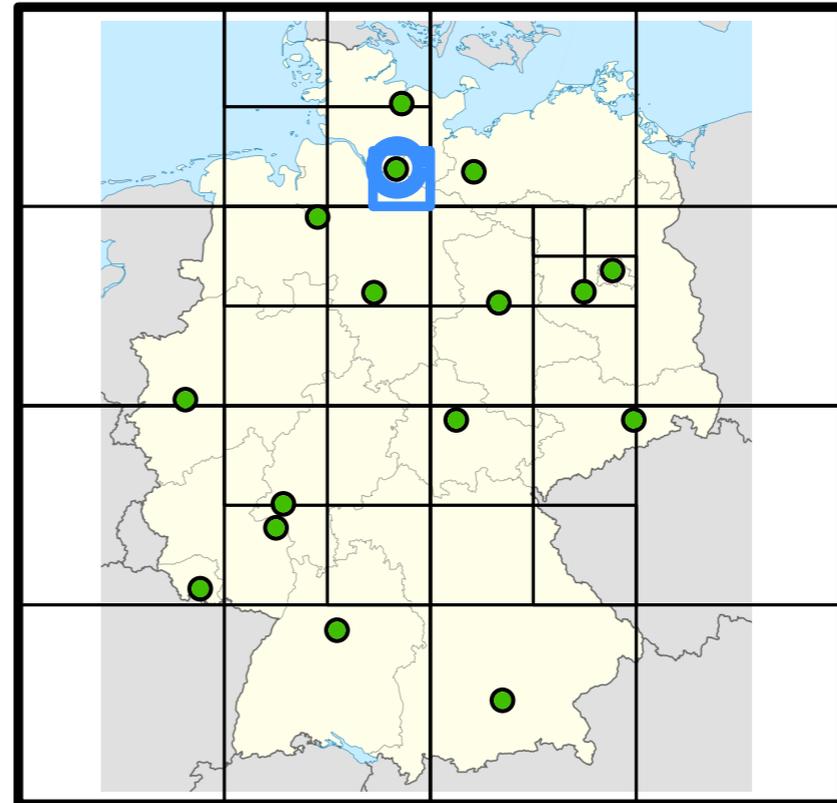


Faster point location:

preprocessing: build hash table using $id(v)$

query: binary search on levels

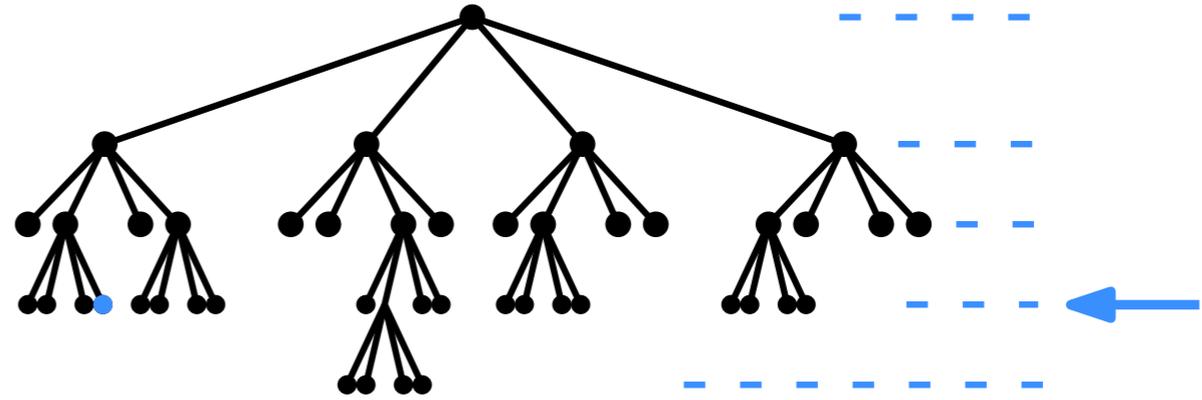
- if inner node: recurse in lower half
- if no node: recurse in upper half



Quadtrees: multi-scale grids

node v at depth i :

- square $S_v \rightarrow$ side length = 2^{-i}
- in grid $G_{2^{-i}}$
- level $\ell(v) = -i$
- $id(v) = (\ell(v), \lfloor x/2^{\ell(v)} \rfloor, \lfloor y/2^{\ell(v)} \rfloor)$,
with (x, y) a point in S_v

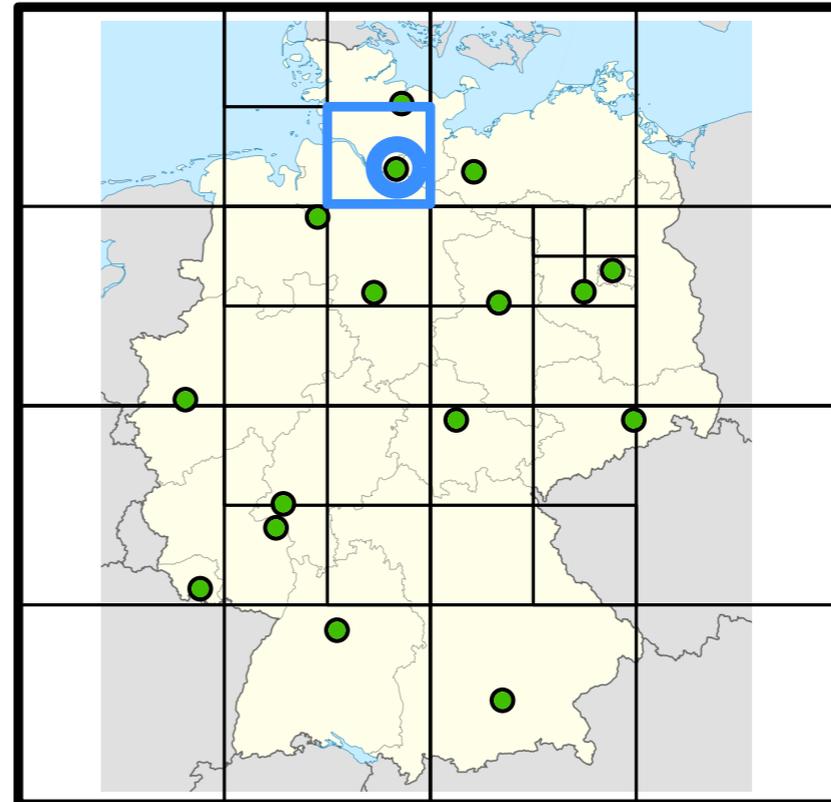


Faster point location:

preprocessing: build hash table using $id(v)$

query: binary search on levels

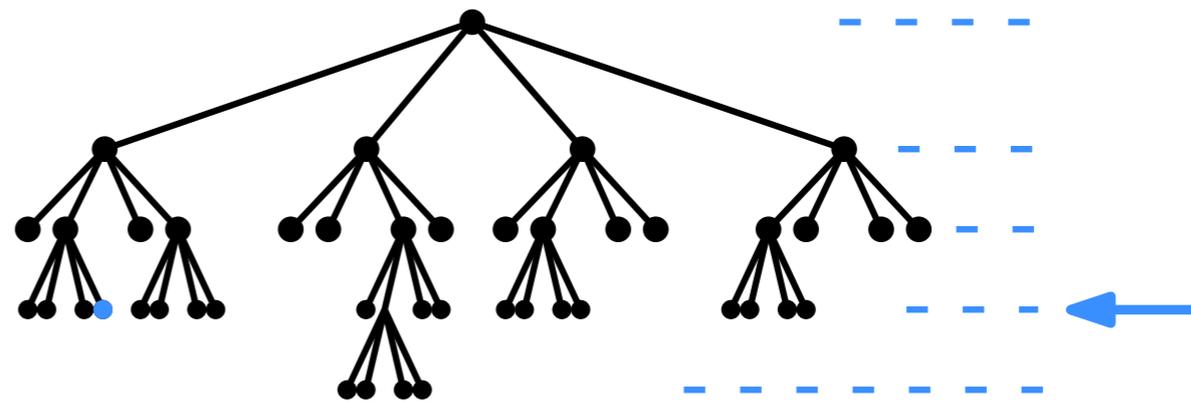
- if inner node: recurse in lower half
- if no node: recurse in upper half
- if leaf: ✓



Quadtrees: multi-scale grids

node v at depth i :

- square $S_v \rightarrow$ side length = 2^{-i}
- in grid $G_{2^{-i}}$
- level $\ell(v) = -i$
- $id(v) = (\ell(v), \lfloor x/2^{\ell(v)} \rfloor, \lfloor y/2^{\ell(v)} \rfloor)$,
with (x, y) a point in S_v



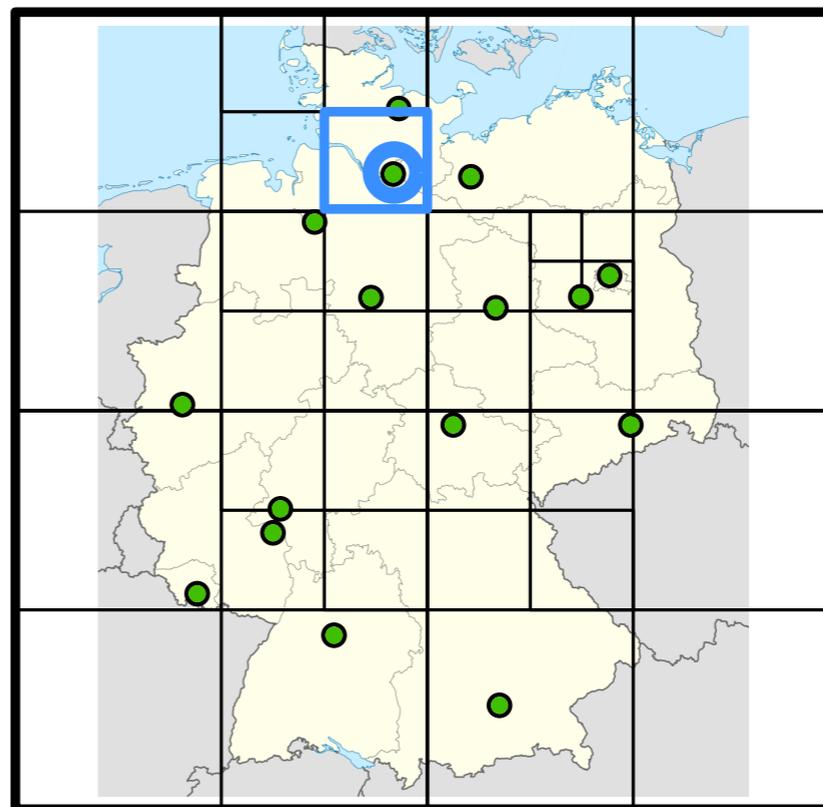
Faster point location:

preprocessing: build hash table using $id(v)$

query: binary search on levels

- if inner node: recurse in lower half
- if no node: recurse in upper half
- if leaf: ✓

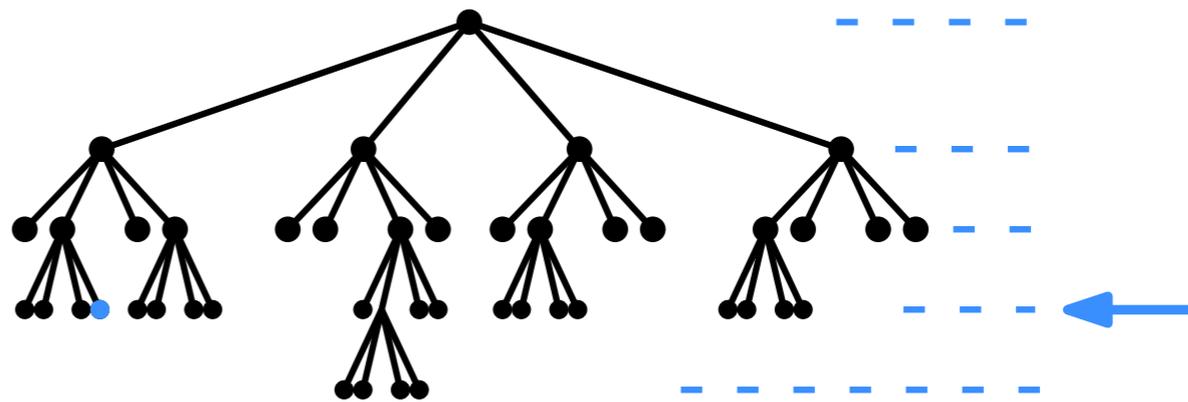
query time: $O(\log d)$



Quadtrees: multi-scale grids

node v at depth i :

- square $S_v \rightarrow$ side length $= 2^{-i}$
- in grid $G_{2^{-i}}$
- level $\ell(v) = -i$
- $id(v) = (\ell(v), \lfloor x/2^{\ell(v)} \rfloor, \lfloor y/2^{\ell(v)} \rfloor)$,
with (x, y) a point in S_v



Faster point location:

preprocessing: build hash table using $id(v)$

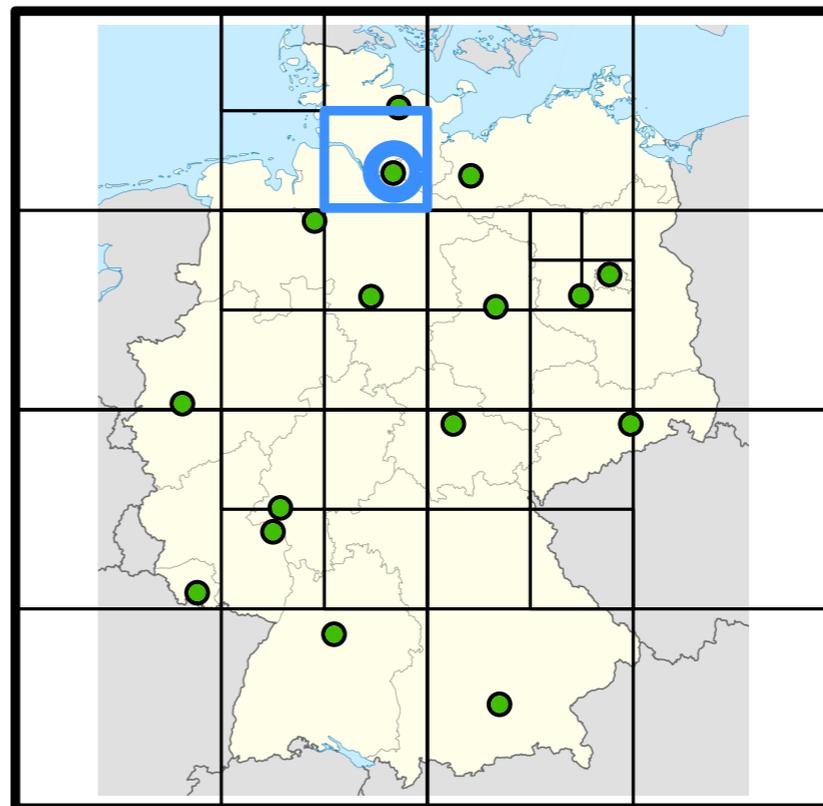
query: binary search on levels

- if inner node: recurse in lower half
- if no node: recurse in upper half
- if leaf: ✓

query time: $O(\log d)$

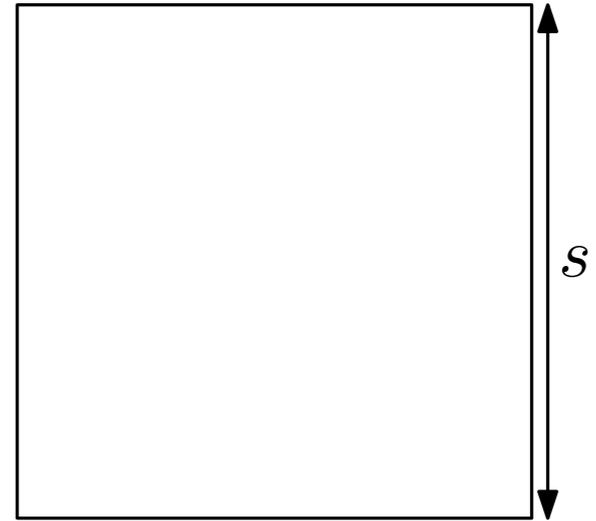


How large is d ? How large is the quadtree?



Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

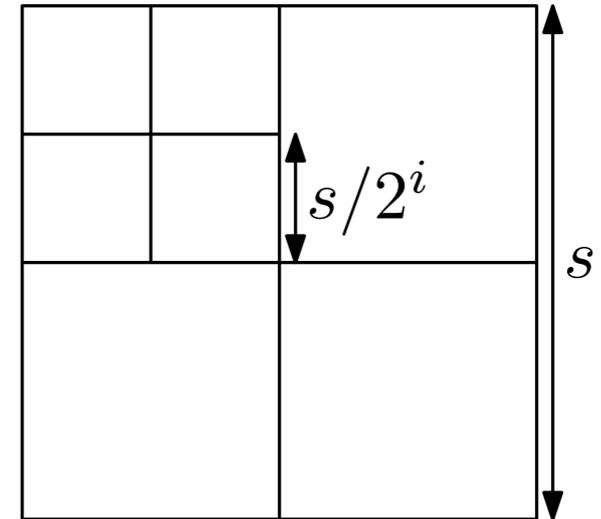


Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

Proof:

- consider square σ of depth i with side length $s/2^i$

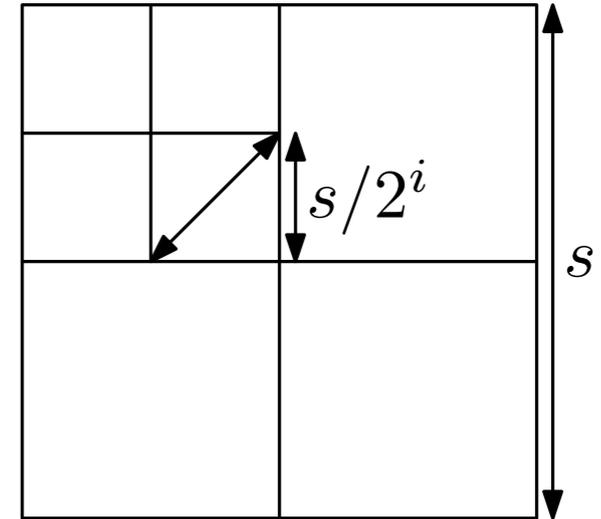


Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

Proof:

- consider square σ of depth i with side length $s/2^i$
- maximum distance between two points in σ : $\sqrt{2}s/2^i$



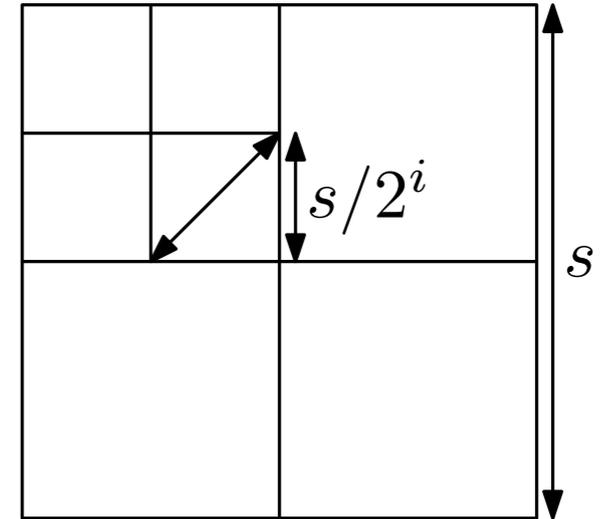
Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

Proof:

- consider square σ of depth i with side length $s/2^i$
- maximum distance between two points in σ : $\sqrt{2}s/2^i$

\Rightarrow if depth of cell with ≥ 2 points is i , $\sqrt{2}s/2^i \geq c$



Quadtree: depth and size

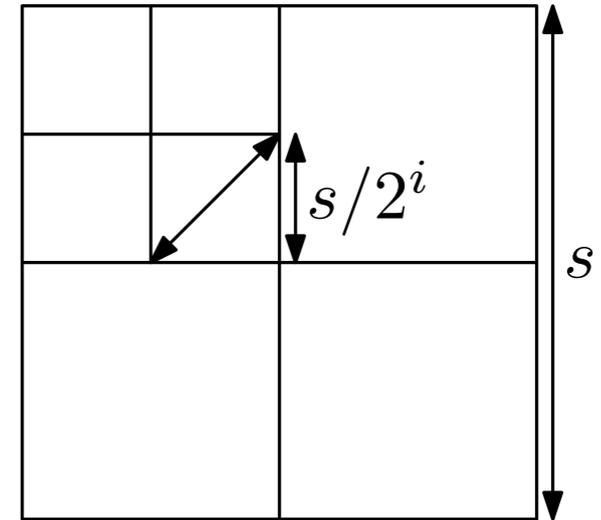
Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

Proof:

- consider square σ of depth i with side length $s/2^i$
- maximum distance between two points in σ : $\sqrt{2}s/2^i$

\Rightarrow if depth of cell with ≥ 2 points is i , $\sqrt{2}s/2^i \geq c$

$$\Rightarrow i \leq \log(\sqrt{2}s/c) = \log(s/c) + 1/2$$



Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

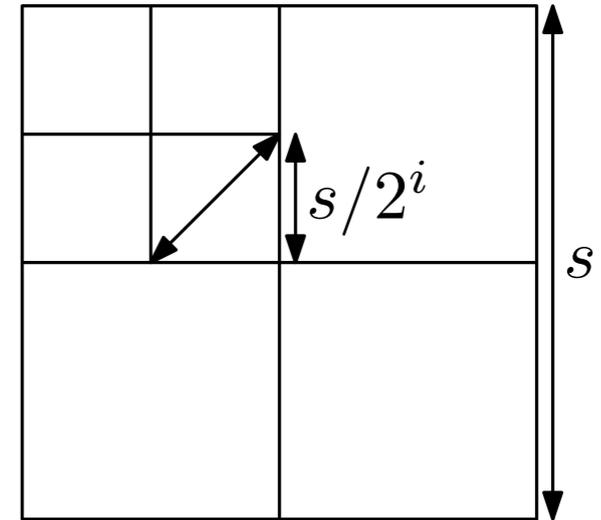
Proof:

- consider square σ of depth i with side length $s/2^i$
- maximum distance between two points in σ : $\sqrt{2}s/2^i$

\Rightarrow if depth of cell with ≥ 2 points is i , $\sqrt{2}s/2^i \geq c$

$$\Rightarrow i \leq \log(\sqrt{2}s/c) = \log(s/c) + 1/2$$

\Rightarrow depth of quadtree $\leq \log(s/c) + 1/2 + 1$, since nodes with ≤ 1 points have no children



Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

Theorem: A quadtree of depth d storing n points has $O((d + 1)n)$ nodes and can be constructed in $O((d + 1)n)$ time.

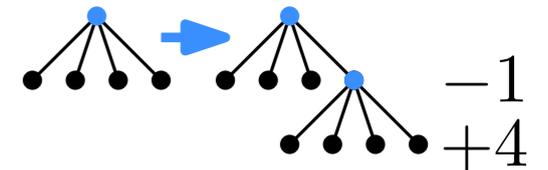
Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

Theorem: A quadtree of depth d storing n points has $O((d + 1)n)$ nodes and can be constructed in $O((d + 1)n)$ time.

Proof:

- Inner nodes have 4 children \Rightarrow #leaves = $1 + 3 \cdot$ #inner nodes



Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

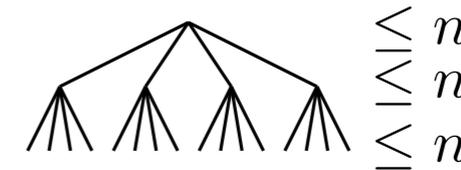
Theorem: A quadtree of depth d storing n points has $O((d + 1)n)$ nodes and can be constructed in $O((d + 1)n)$ time.

Proof:

- Inner nodes have 4 children \Rightarrow #leaves = $1 + 3 \cdot$ #inner nodes

- Inner nodes correspond to disjoint squares with ≥ 2 points

$\Rightarrow \leq n$ squares per layer corresponding to inner nodes



Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

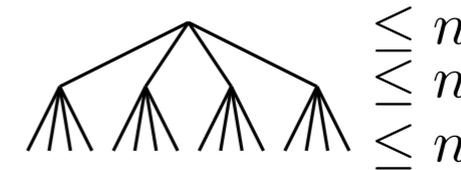
Theorem: A quadtree of depth d storing n points has $O((d + 1)n)$ nodes and can be constructed in $O((d + 1)n)$ time.

Proof:

- Inner nodes have 4 children \Rightarrow #leaves = $1 + 3 \cdot$ #inner nodes

- Inner nodes correspond to disjoint squares with ≥ 2 points

$\Rightarrow \leq n$ squares per layer corresponding to inner nodes



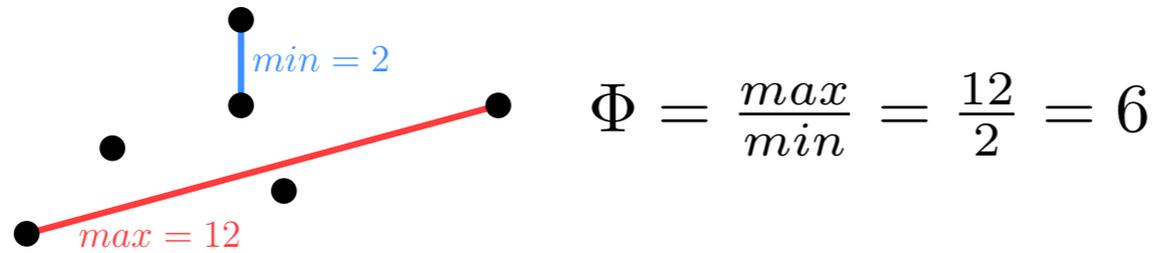
\Rightarrow for depth d overall $O((d + 1)n)$ nodes.

Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

Theorem: A quadtree of depth d storing n points has $O((d + 1)n)$ nodes and can be constructed in $O((d + 1)n)$ time.

Definition: The spread of point set P is $\Phi(P) = \frac{\max_{p,q \in P} \|p - q\|}{\min_{p,q \in P, p \neq q} \|p - q\|}$

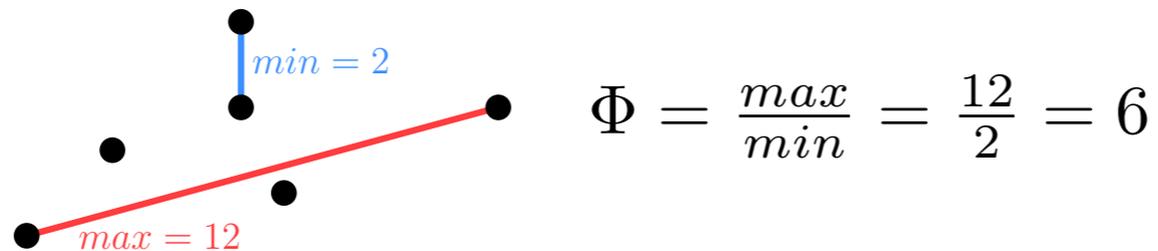


Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

Theorem: A quadtree of depth d storing n points has $O((d + 1)n)$ nodes and can be constructed in $O((d + 1)n)$ time.

Definition: The spread of point set P is $\Phi(P) = \frac{\max_{p,q \in P} \|p - q\|}{\min_{p,q \in P, p \neq q} \|p - q\|}$



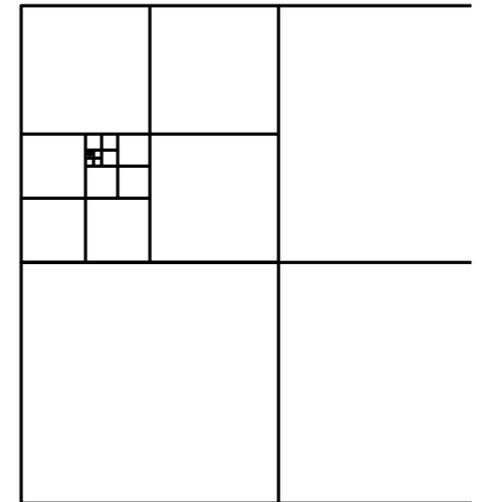
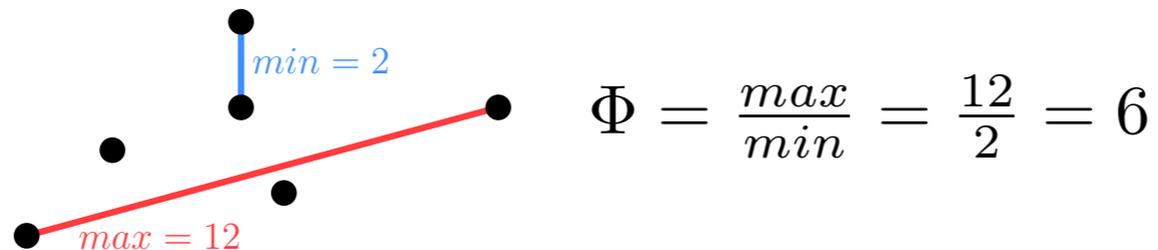
Observation: The depth of a quadtree is in $O(\log(\Phi(P)))$ and the size in $O(n \log \Phi(P))$.

Quadtree: depth and size

Lemma: Let c be the smallest distance between any two points in a point set P , and let s be the side length of the initial (biggest) square. Then the depth of a quadtree for P is at most $\log(s/c) + 3/2$.

Theorem: A quadtree of depth d storing n points has $O((d + 1)n)$ nodes and can be constructed in $O((d + 1)n)$ time.

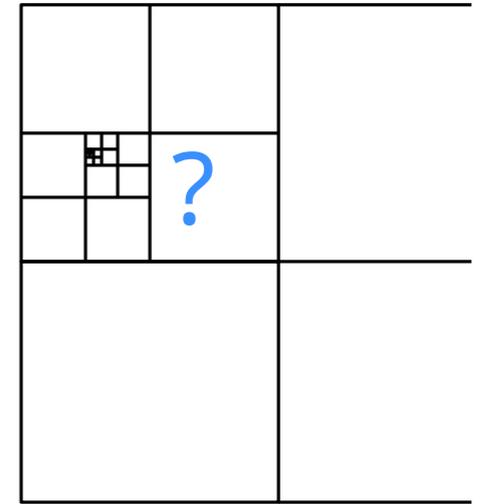
Definition: The spread of point set P is $\Phi(P) = \frac{\max_{p,q \in P} \|p - q\|}{\min_{p,q \in P, p \neq q} \|p - q\|}$



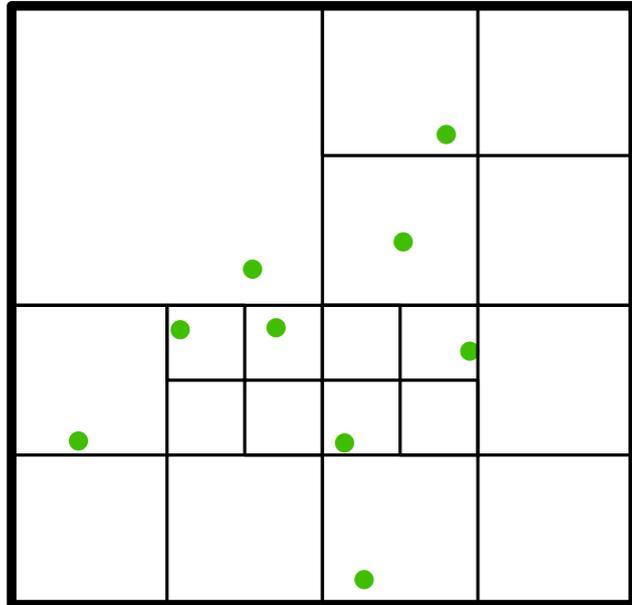
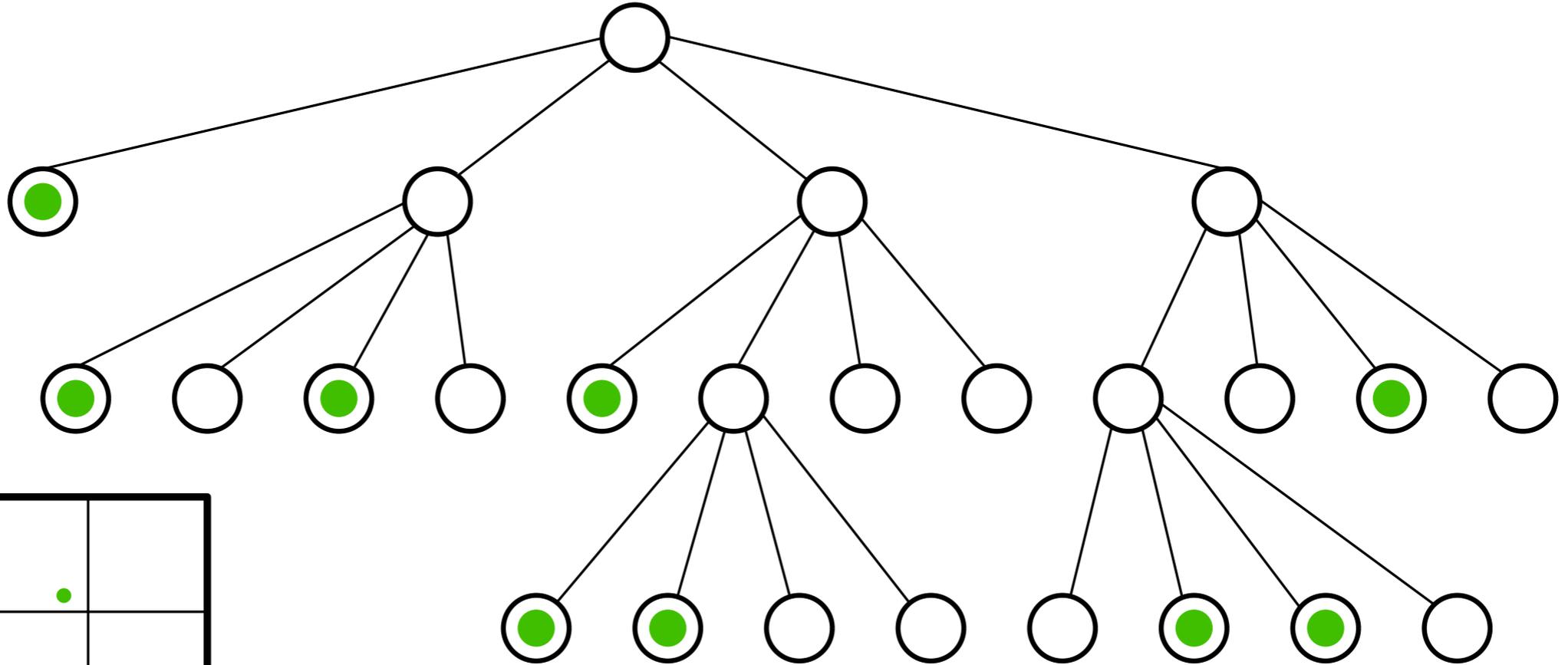
Observation: The depth of a quadtree is in $O(\log(\Phi(P)))$ and the size in $O(n \log \Phi(P))$.

How can we handle the case when $\Phi(P)$ is not bounded by a polynomial in n ? Can we get a linear-size data structure?

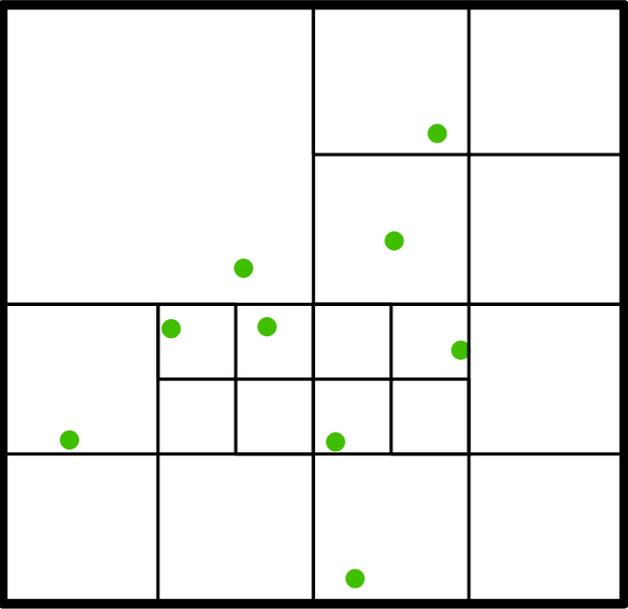
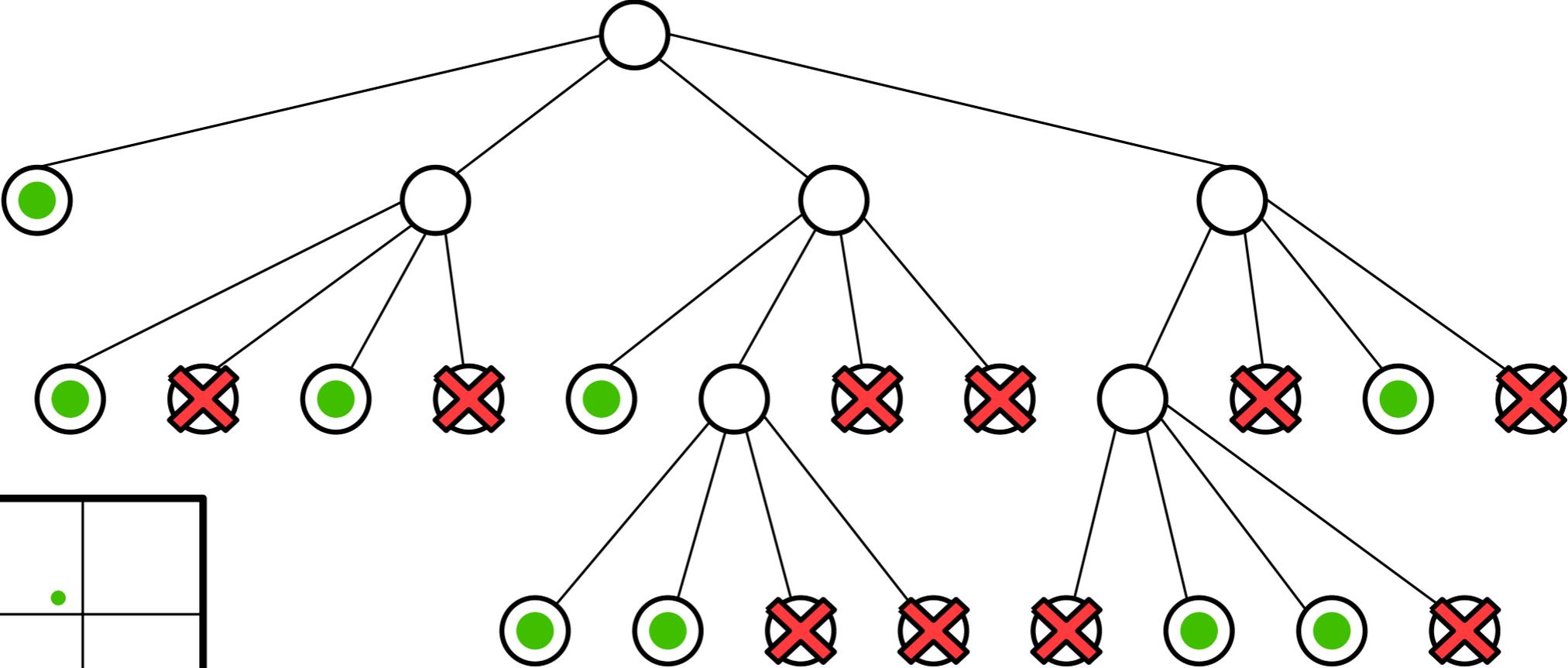
Compressed Quadtrees



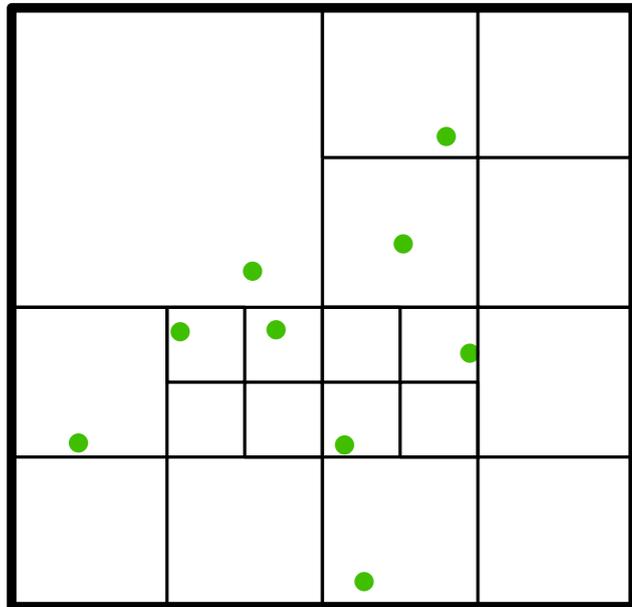
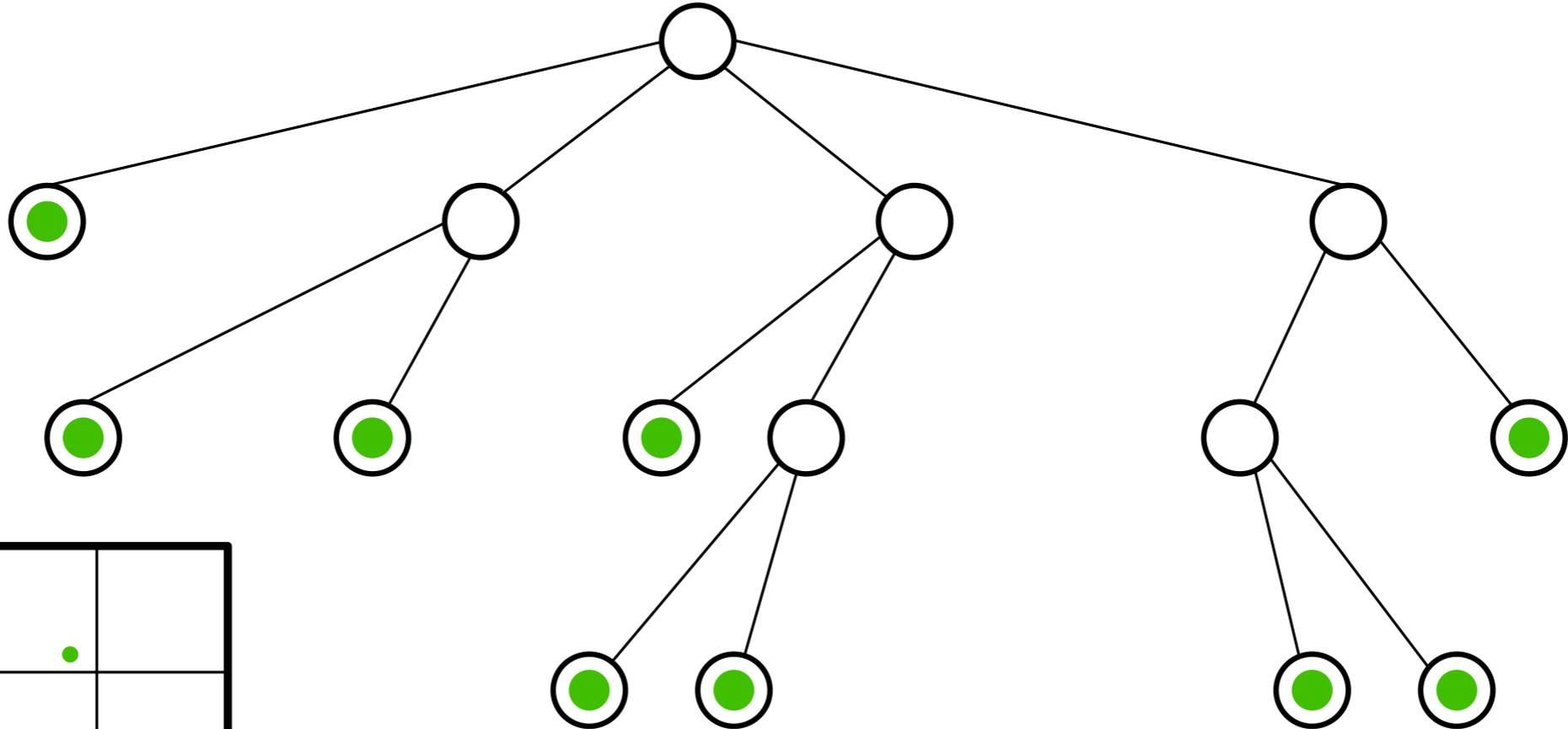
Improving the size, step 0



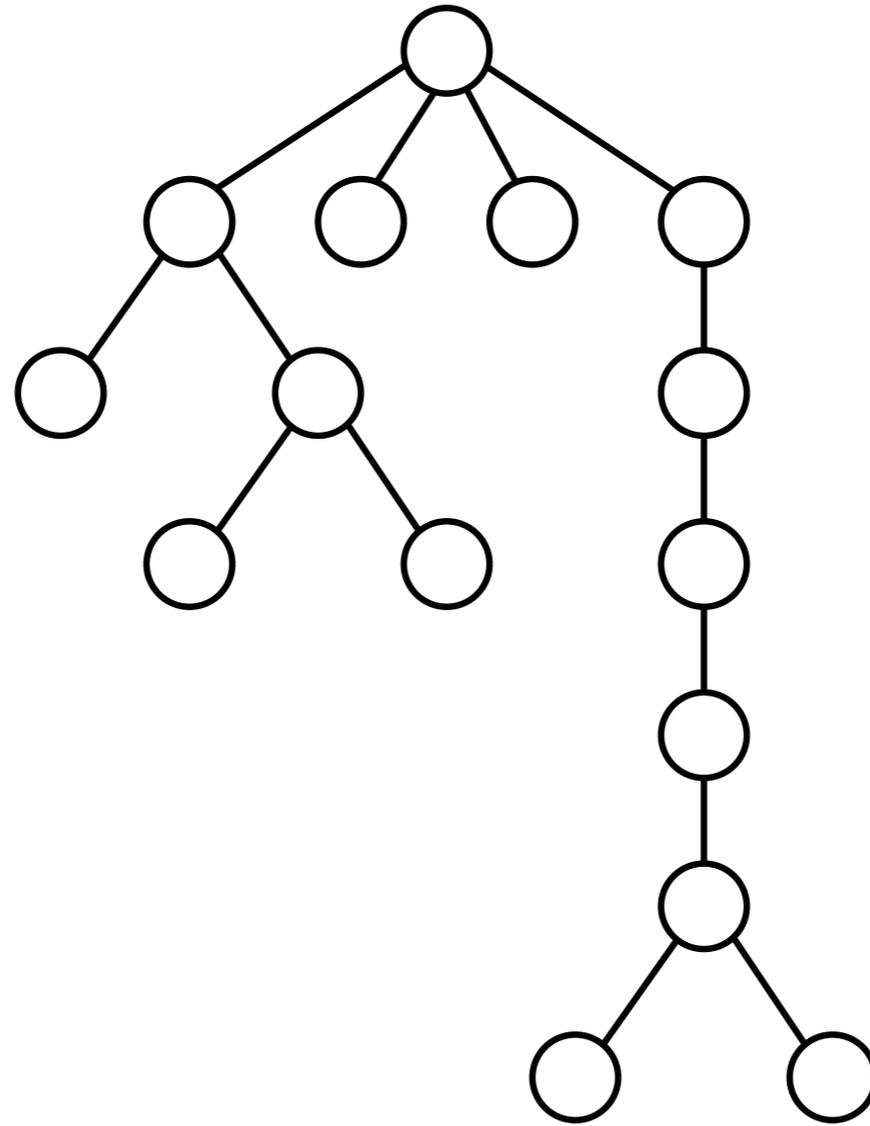
Improving the size, step 0



Improving the size, step 0



Compressed Quadtrees



$$\ell(v) = 0$$

$$\ell(v) = -1$$

$$\ell(v) = -2$$

$$\ell(v) = -3$$

$$\ell(v) = -4$$

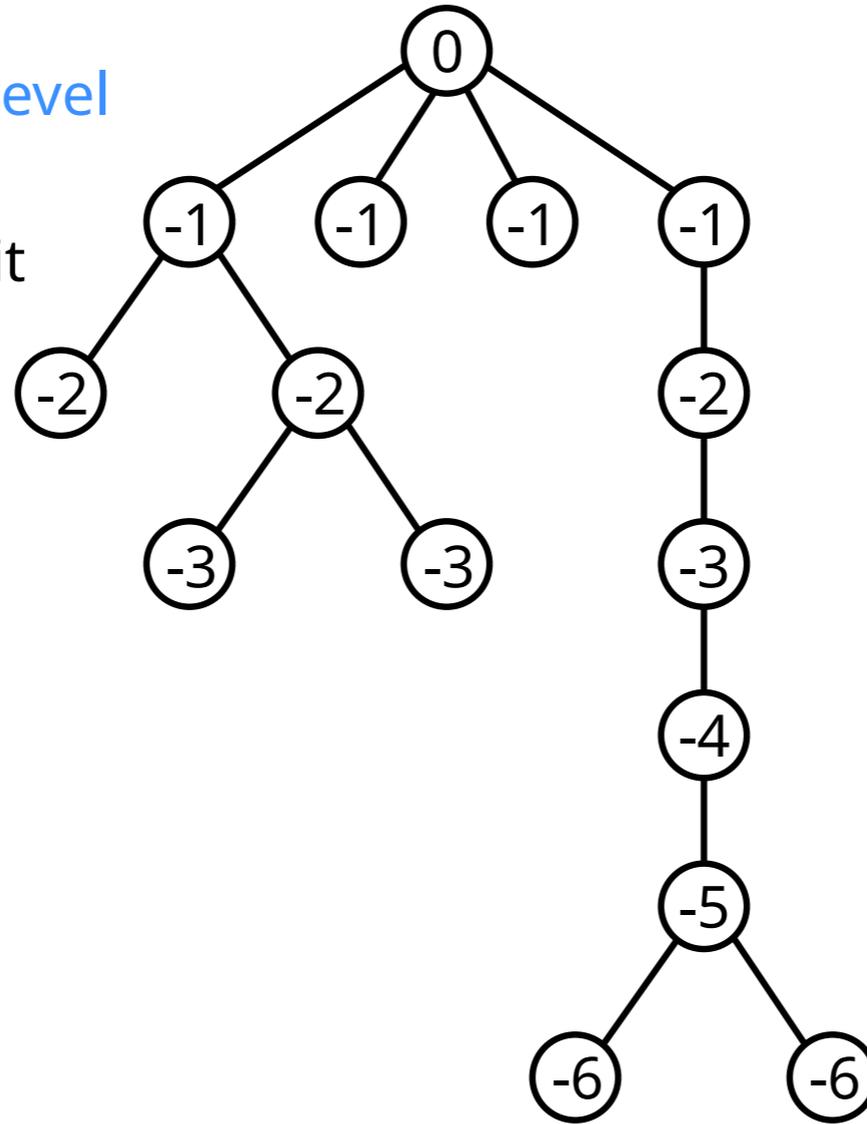
$$\ell(v) = -5$$

$$\ell(v) = -6$$

Compressed Quadrees

Each node gets:

- An integer denoting its **level** in the original quadtree
- A pointer to the **square** it represents.



$$\ell(v) = 0$$

$$\ell(v) = -1$$

$$\ell(v) = -2$$

$$\ell(v) = -3$$

$$\ell(v) = -4$$

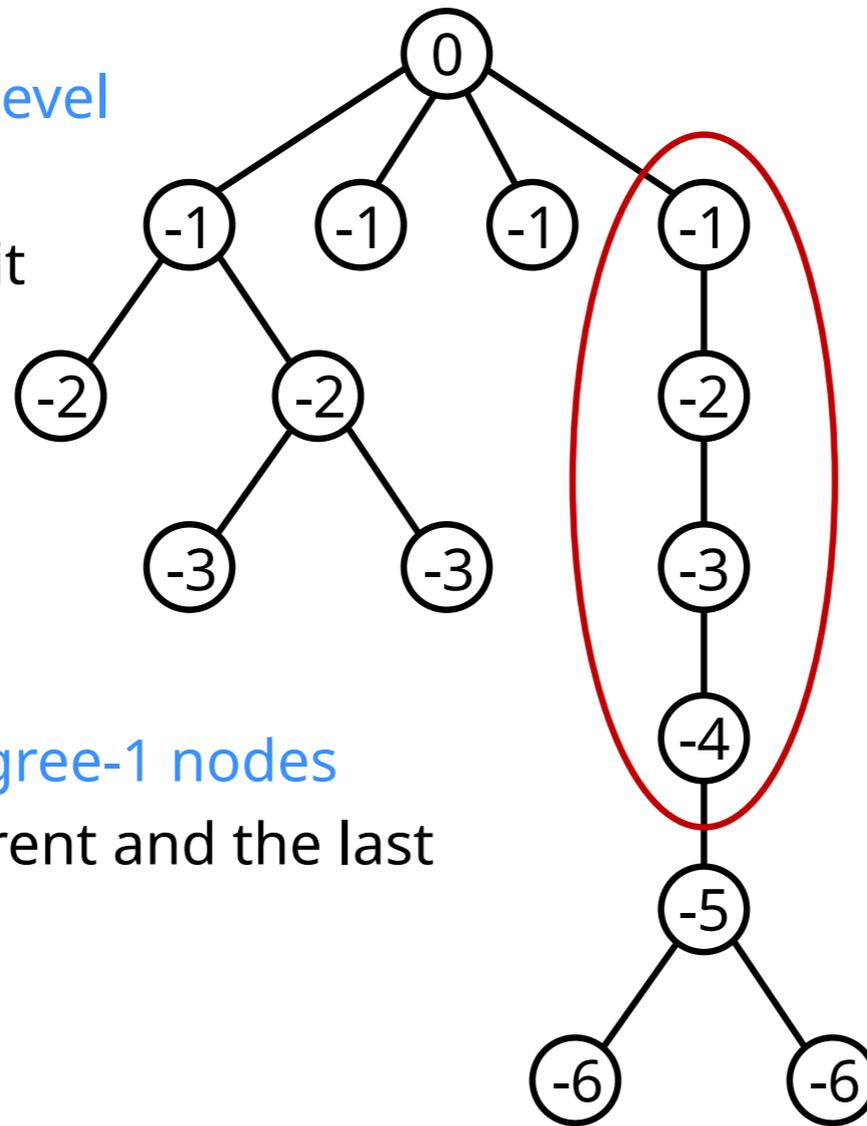
$$\ell(v) = -5$$

$$\ell(v) = -6$$

Compressed Quadrees

Each node gets:

- An integer denoting its **level** in the original quadtree
- A pointer to the **square** it represents.



$$\ell(v) = 0$$

$$\ell(v) = -1$$

$$\ell(v) = -2$$

$$\ell(v) = -3$$

$$\ell(v) = -4$$

$$\ell(v) = -5$$

$$\ell(v) = -6$$

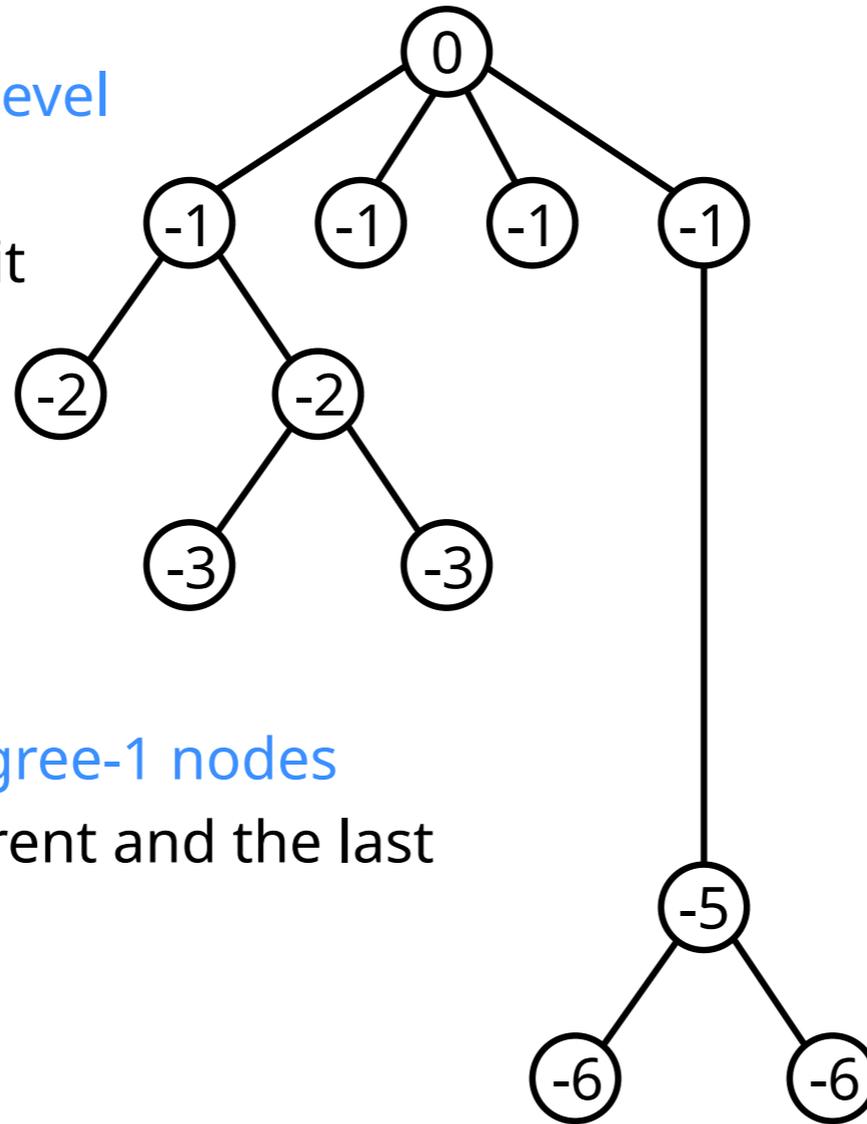
Paths consisting of only **degree-1 nodes**

\implies replace by the first parent and the last child on the path.

Compressed Quadtrees

Each node gets:

- An integer denoting its **level** in the original quadtree
- A pointer to the **square** it represents.



$$\ell(v) = 0$$

$$\ell(v) = -1$$

$$\ell(v) = -2$$

$$\ell(v) = -3$$

$$\ell(v) = -4$$

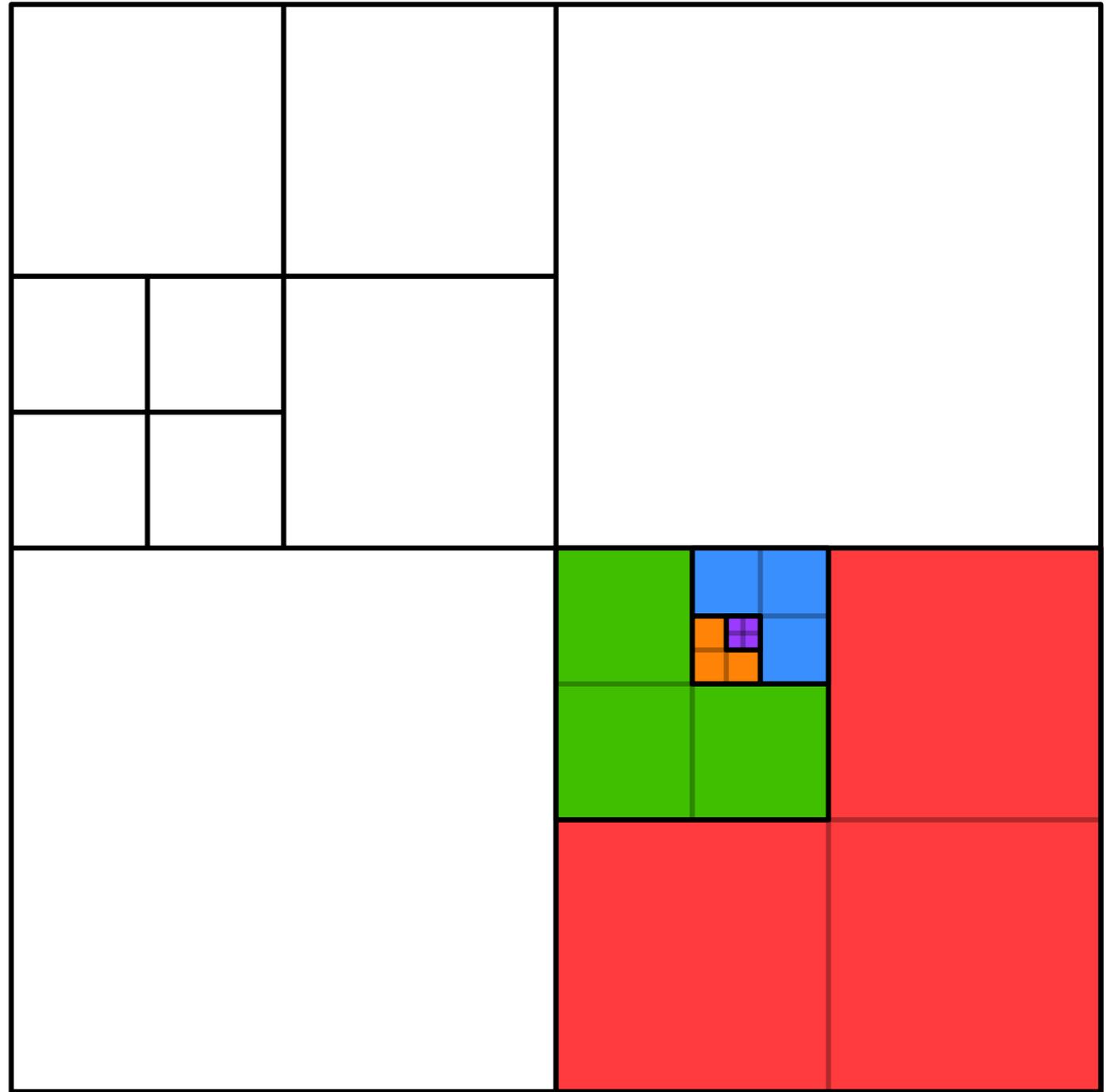
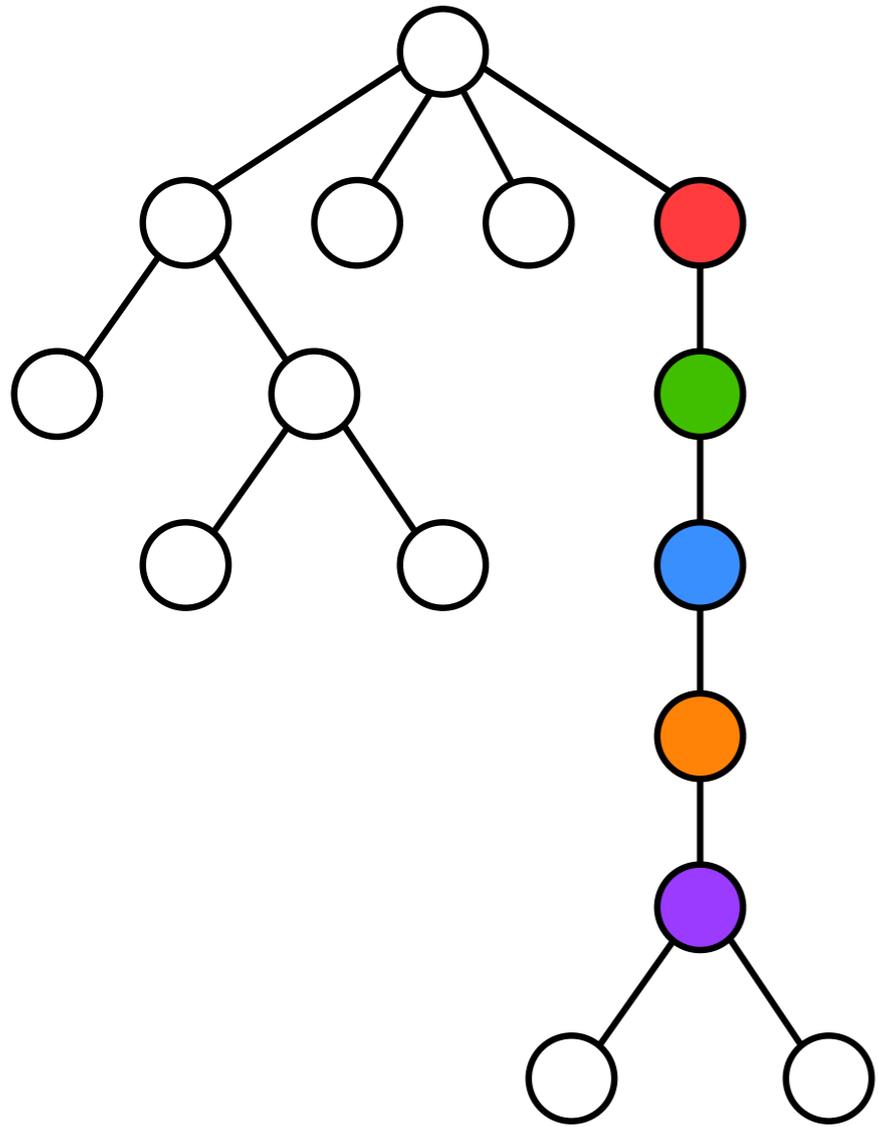
$$\ell(v) = -5$$

$$\ell(v) = -6$$

Paths consisting of only **degree-1 nodes**

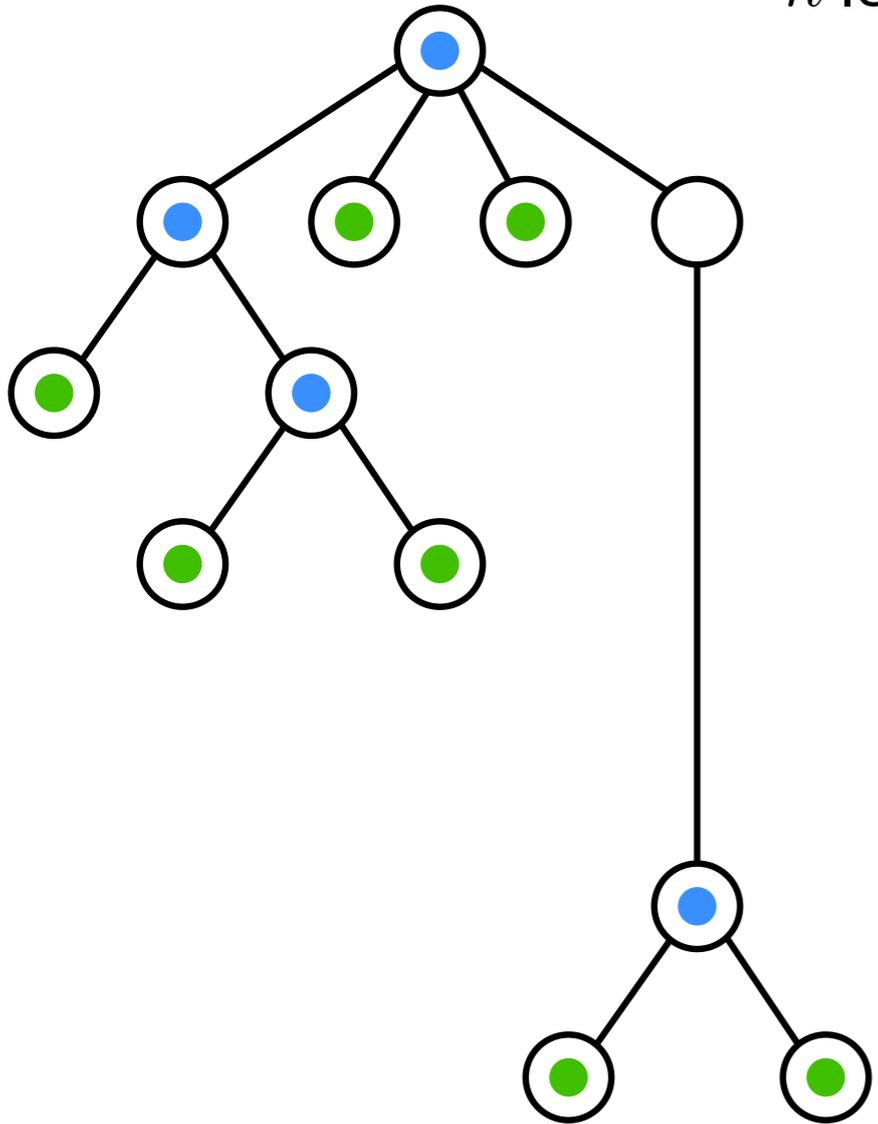
\implies replace by the first parent and the last child on the path.

Merging squares



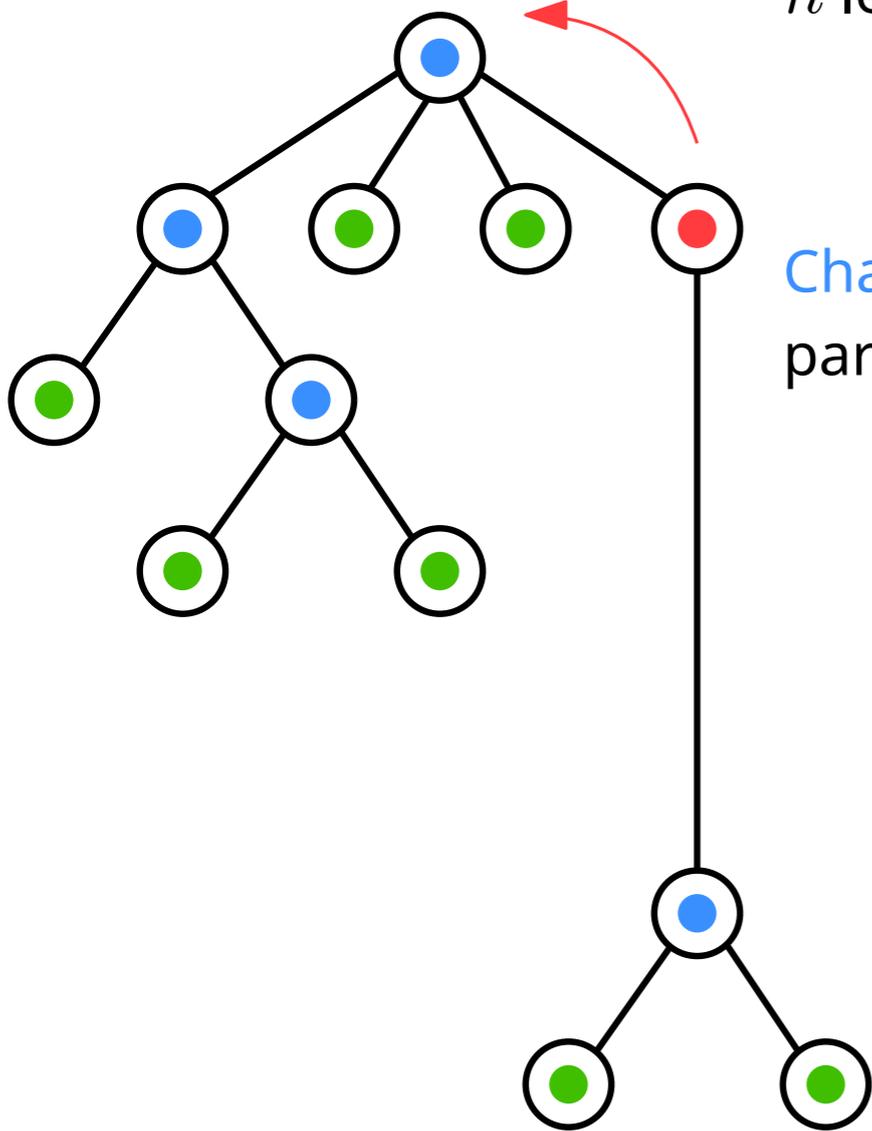
Size of compressed quadtree

n leaves \Rightarrow at most $n - 1$ internal nodes with degree ≥ 2



Size of compressed quadtree

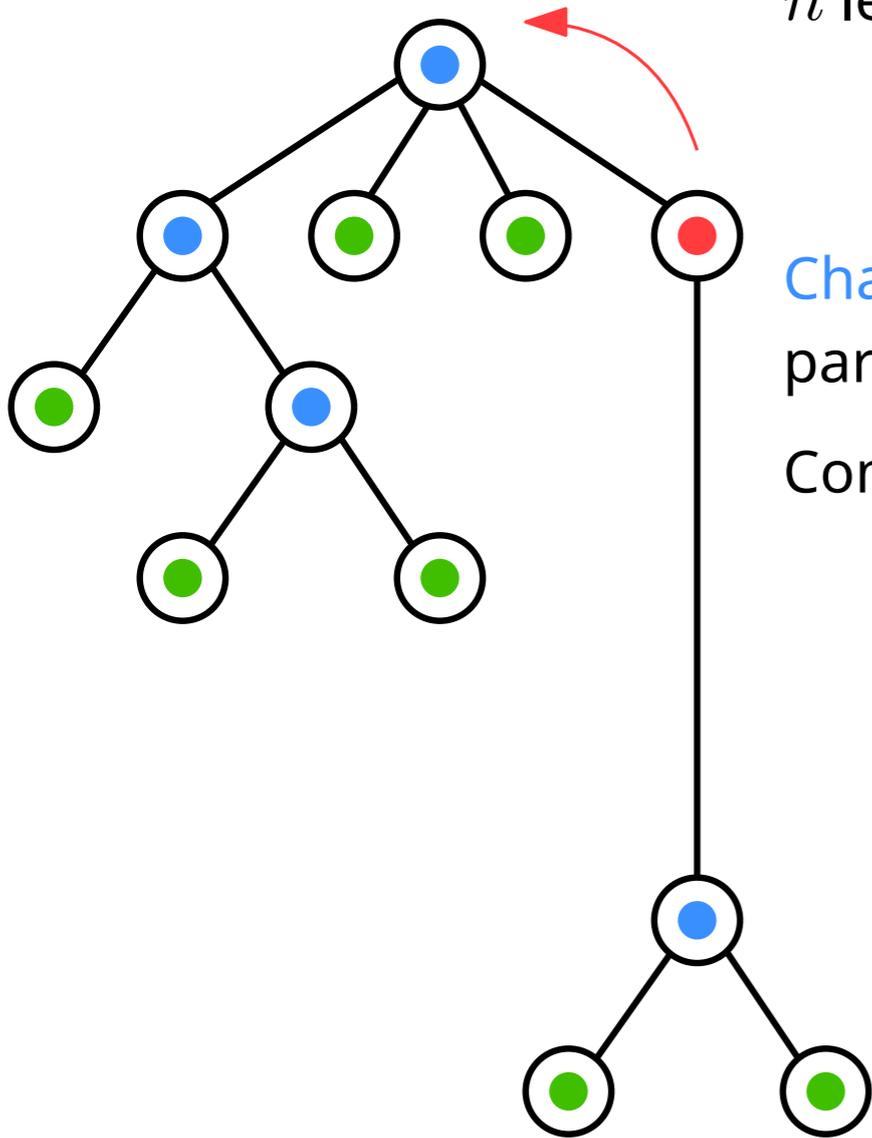
n leaves \Rightarrow at most $n - 1$ internal nodes with degree ≥ 2



Charging argument: Charge any node with a single child to its parent, which has 2 or more children because of compression

Size of compressed quadtree

n leaves \Rightarrow at most $n - 1$ internal nodes with degree ≥ 2



Charging argument: Charge any node with a single child to its parent, which has 2 or more children because of compression

Compressed quadtrees have **linear** size!

Efficient construction

Simple recursive construction on compressed quadtrees has **unbounded** time complexity when the **spread** of the point set is unbounded.

We can do better with a **divide and conquer** approach!

Efficient construction

Simple recursive construction on compressed quadtrees has **unbounded** time complexity when the **spread** of the point set is unbounded.

We can do better with a **divide and conquer** approach!

Idea: Find a square (in a grid $G_{2^{-i}}$) that contains a constant fraction of the points.

Efficient construction

Simple recursive construction on compressed quadtrees has **unbounded** time complexity when the **spread** of the point set is unbounded.

We can do better with a **divide and conquer** approach!

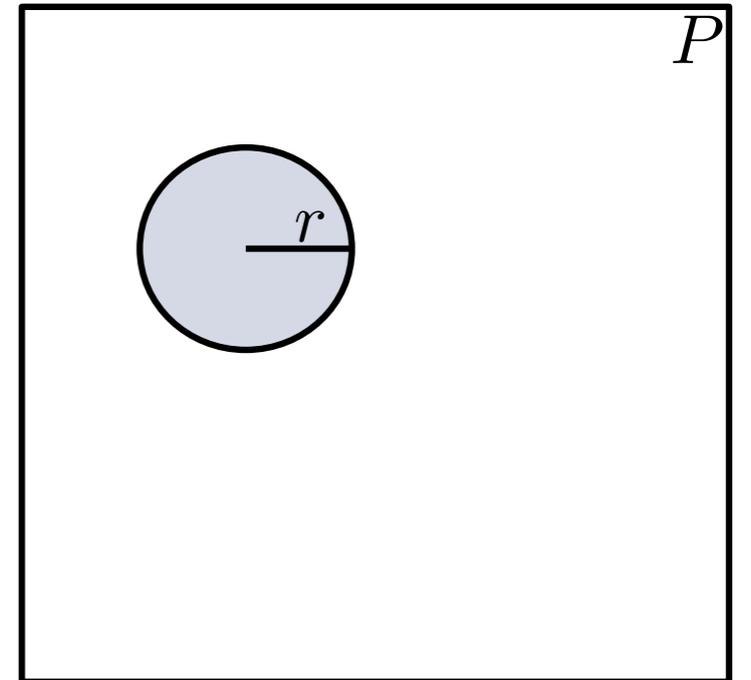
Idea: Find a square (in a grid $G_{2^{-i}}$) that contains a constant fraction of the points.

Theorem: In linear time we can compute a disk D containing $n/10$ points with radius $r_D \leq 2r_{OPT}$, where r_{OPT} is the radius of the smallest disk containing $n/10$ points.

Question: Which algorithm(s) do you know to compute this disk?

Efficient construction

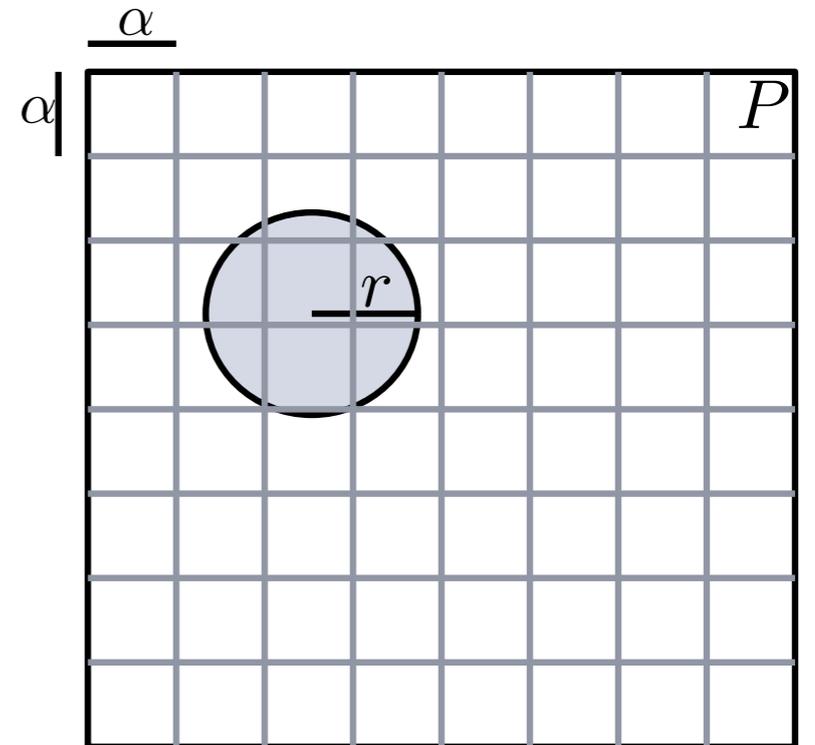
Theorem: In linear time we can compute a disk D containing $n/10$ points with radius $r_D \leq 2r_{OPT}$, where r_{OPT} is the radius of the smallest disk containing $n/10$ points.



Efficient construction

Theorem: In linear time we can compute a disk D containing $n/10$ points with radius $r_D \leq 2r_{OPT}$, where r_{OPT} is the radius of the smallest disk containing $n/10$ points.

$$\alpha = 2^{\lceil \log_2(r) \rceil}$$



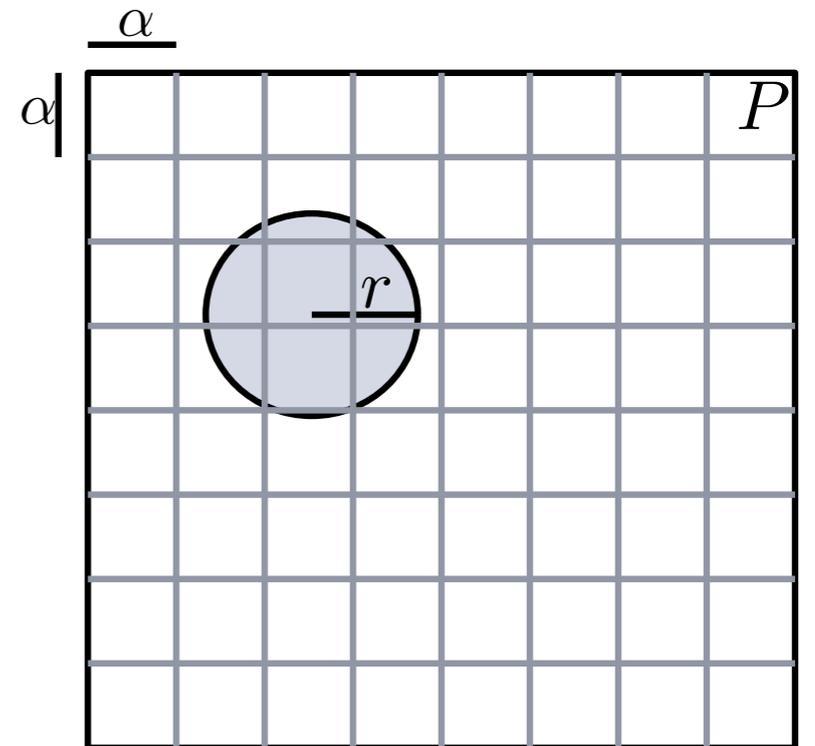
Efficient construction

Theorem: In linear time we can compute a disk D containing $n/10$ points with radius $r_D \leq 2r_{OPT}$, where r_{OPT} is the radius of the smallest disk containing $n/10$ points.

$$\alpha = 2^{\lceil \log_2(r) \rceil}$$

$$r \geq \alpha \geq r/2$$

$\implies D$ is covered by **at most** 25 grid cells



Efficient construction

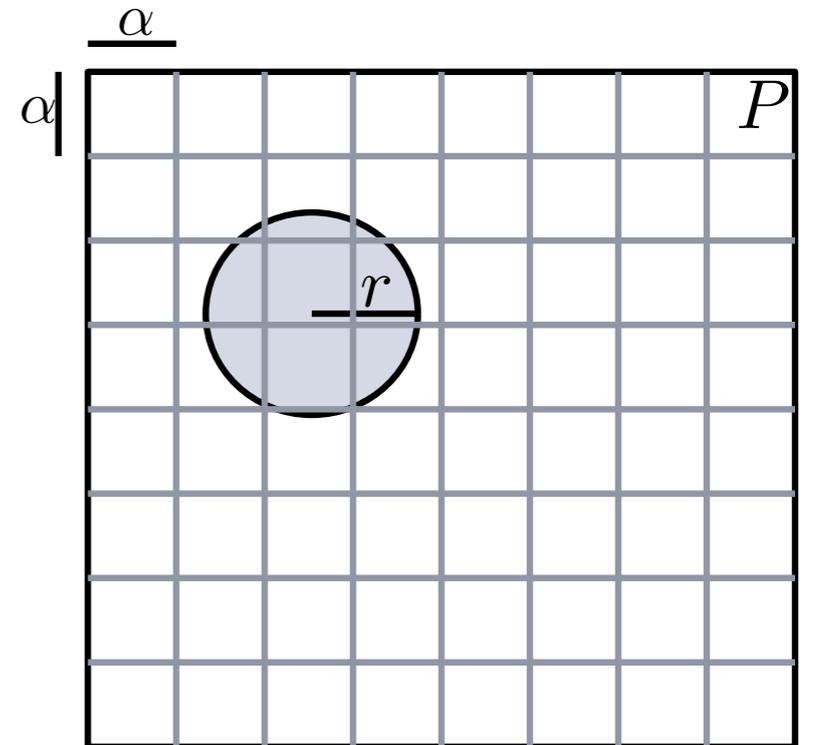
Theorem: In linear time we can compute a disk D containing $n/10$ points with radius $r_D \leq 2r_{OPT}$, where r_{OPT} is the radius of the smallest disk containing $n/10$ points.

$$\alpha = 2^{\lceil \log_2(r) \rceil}$$

$$r \geq \alpha \geq r/2$$

$\implies D$ is covered by **at most** 25 grid cells

$\implies \exists$ a cell c containing **at least** $\frac{n/10}{25}$ points



Efficient construction

Theorem: In linear time we can compute a disk D containing $n/10$ points with radius $r_D \leq 2r_{OPT}$, where r_{OPT} is the radius of the smallest disk containing $n/10$ points.

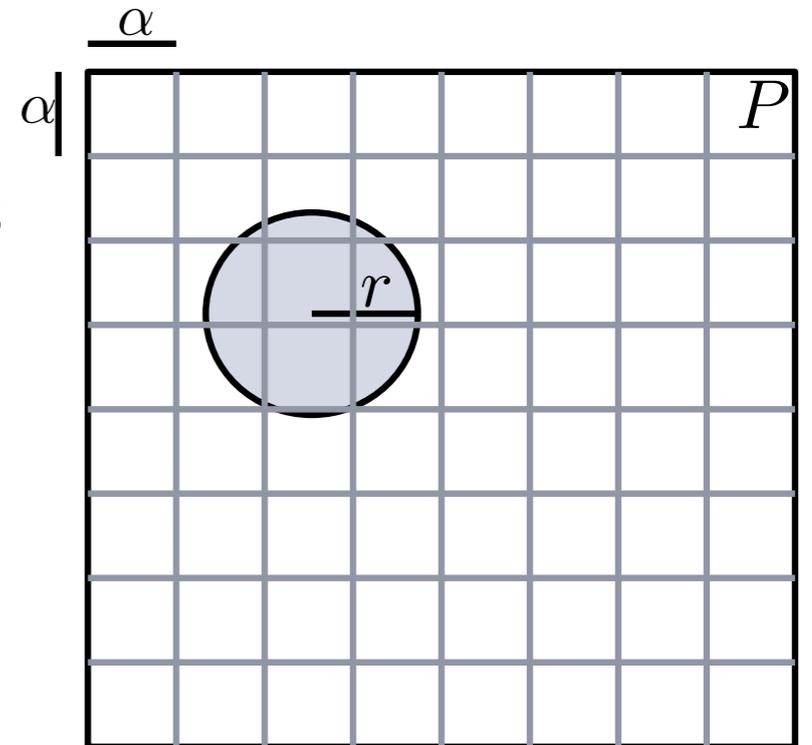
$$\alpha = 2^{\lceil \log_2(r) \rceil}$$

$$r \geq \alpha \geq r/2$$

$\implies D$ is covered by **at most** 25 grid cells

$\implies \exists$ a cell c containing **at least** $\frac{n/10}{25}$ points

Lemma: No cell contains more than $5 \cdot n/10 = n/2$ points



Efficient construction

Theorem: In linear time we can compute a disk D containing $n/10$ points with radius $r_D \leq 2r_{OPT}$, where r_{OPT} is the radius of the smallest disk containing $n/10$ points.

$$\alpha = 2^{\lceil \log_2(r) \rceil}$$

$$r \geq \alpha \geq r/2$$

$\implies D$ is covered by **at most** 25 grid cells

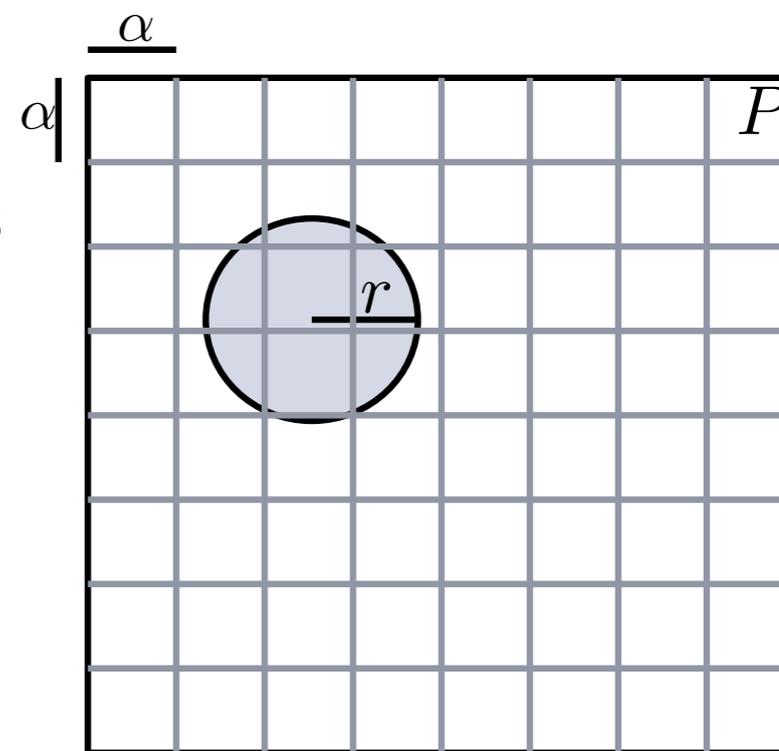
$\implies \exists$ a cell c containing **at least** $\frac{n/10}{25}$ points

Lemma: No cell contains more than $5 \cdot n/10 = n/2$ points

Let \square denote the cell containing the largest number of points.

$$P_{in} = P \cap \square \text{ and } P_{out} = P \setminus P_{in}$$

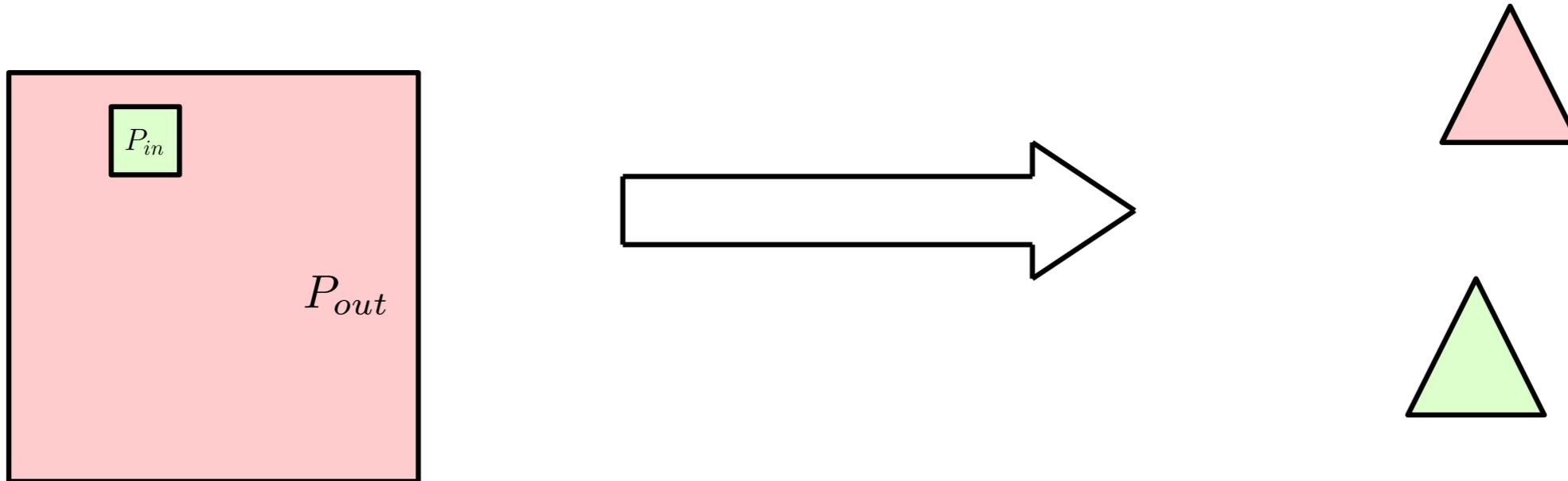
Note that $|P_{in}| \geq n/250$ and $|P_{out}| \geq n/2$



Efficient construction

$$P_{in} = P \cap \square \text{ and } P_{out} = P \setminus P_{in}$$

Recursively construct quadtrees for P_{in} and P_{out}

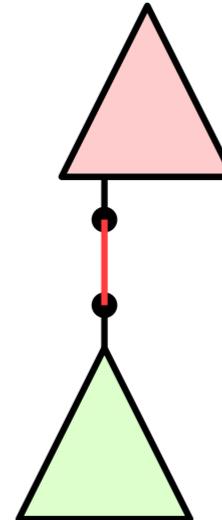
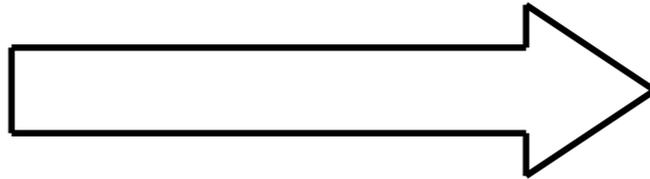
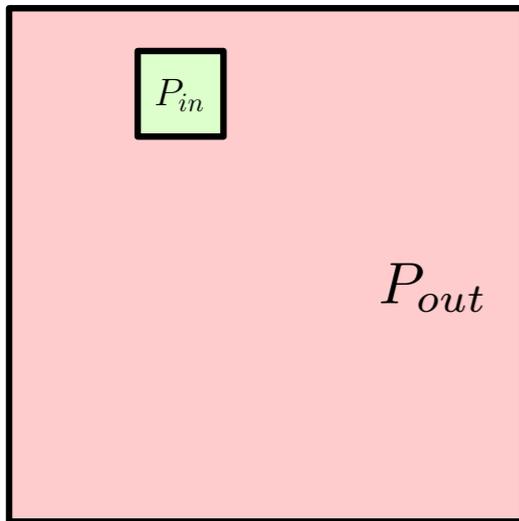


Efficient construction

$$P_{in} = P \cap \square \text{ and } P_{out} = P \setminus P_{in}$$

Recursively construct quadtrees for P_{in} and P_{out}

Create a node representing \square in both quadtrees.

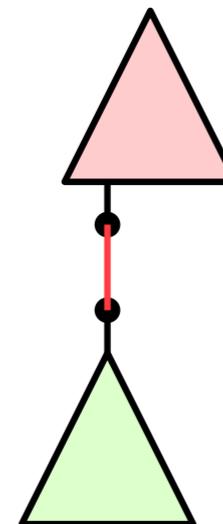
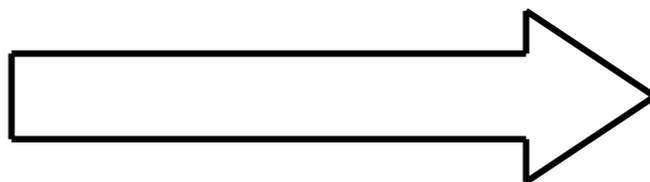
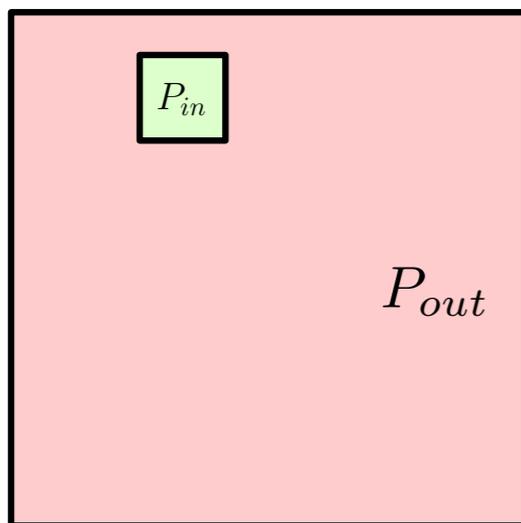


Efficient construction

$$P_{in} = P \cap \square \text{ and } P_{out} = P \setminus P_{in}$$

Recursively construct quadtrees for P_{in} and P_{out}

Create a node representing \square in both quadtrees.



$$\text{Construction time: } T(n) = O(n) + T(|P_{in}|) + T(|P_{out}|) = O(n \log n)$$

Quiz

What is the maximum depth that a quadtree on n points can have?

A $\Theta(\log n)$

B $\Theta(\sqrt{n})$

C $\Theta(n)$

Quiz

What is the maximum depth that a quadtree on n points can have?

A $\Theta(\log n)$

B $\Theta(\sqrt{n})$

C $\Theta(n)$

Question: How does such a quadtree look like?

Point-location on compressed quadtrees

Given a [compressed quadtree](#) T of size n , find lowest node in the tree containing point q .

Point-location on compressed quadtrees

Given a **compressed quadtree** T of size n , find lowest node in the tree containing point q .

May take $\Omega(n)$ time!

Point-location on compressed quadtrees

Given a **compressed quadtree** T of size n , find lowest node in the tree containing point q .

May take $\Omega(n)$ time!

Alternative: preprocess T into a **balanced** tree T' with cross-pointers to T .

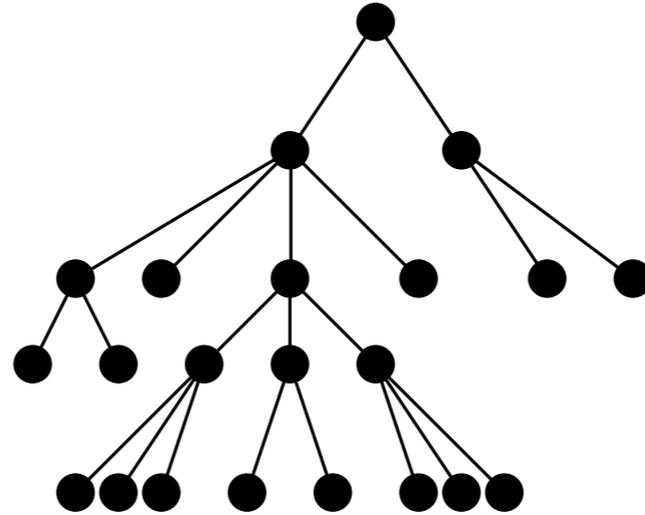
Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.

Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.

Claim: Any tree T **always** contains a separator.

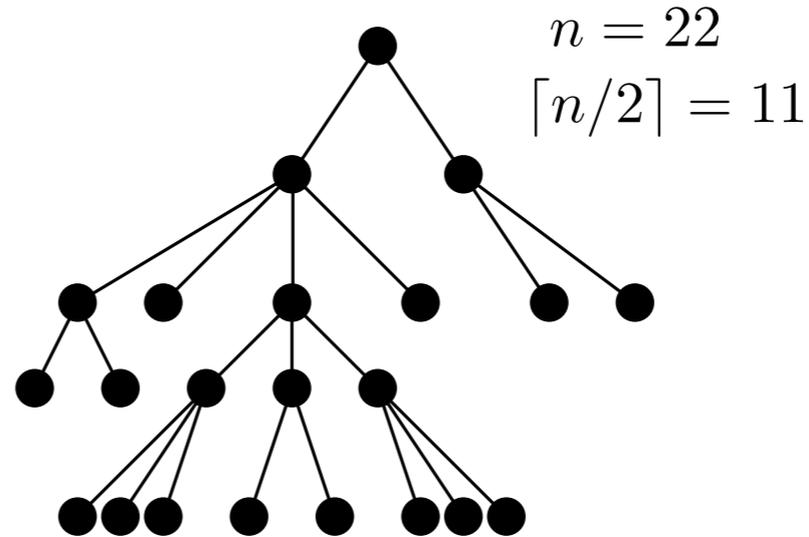


Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.

Claim: Any tree T **always** contains a separator.

Walk through the tree starting at root, going into the subtree that contains $\geq \lceil n/2 \rceil$ nodes.

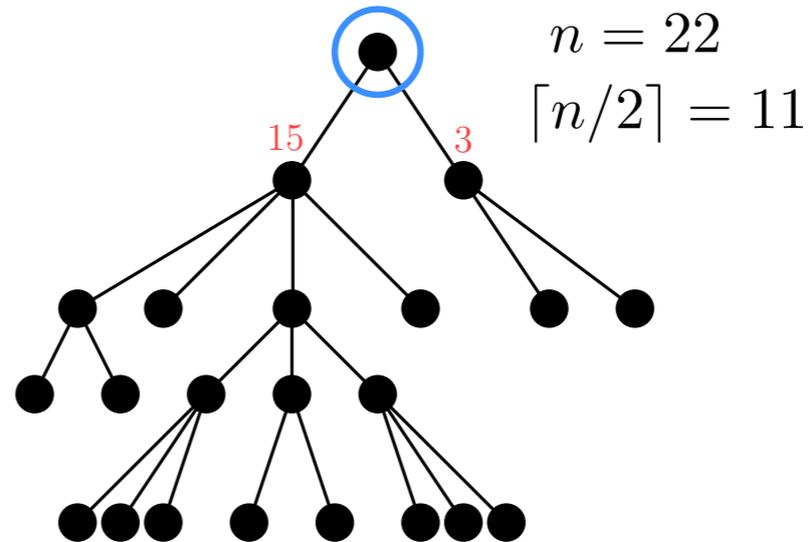


Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.

Claim: Any tree T **always** contains a separator.

Walk through the tree starting at root, going into the subtree that contains $\geq \lceil n/2 \rceil$ nodes.

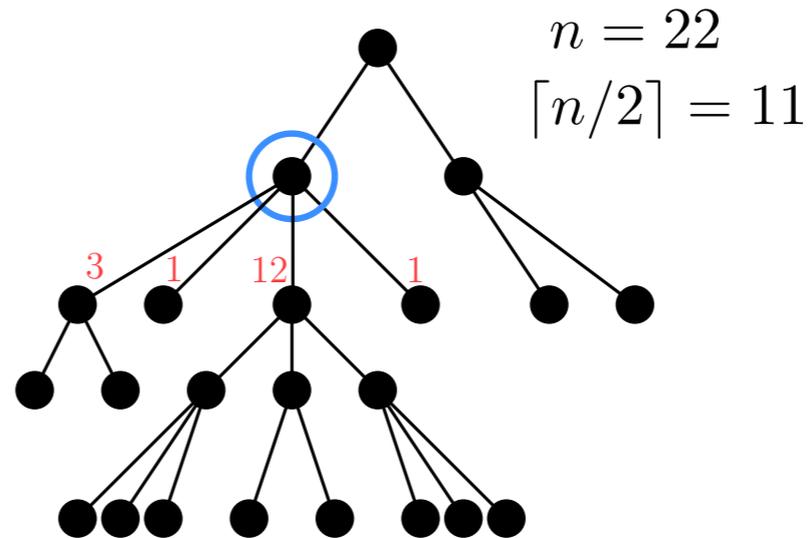


Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.

Claim: Any tree T **always** contains a separator.

Walk through the tree starting at root, going into the subtree that contains $\geq \lceil n/2 \rceil$ nodes.

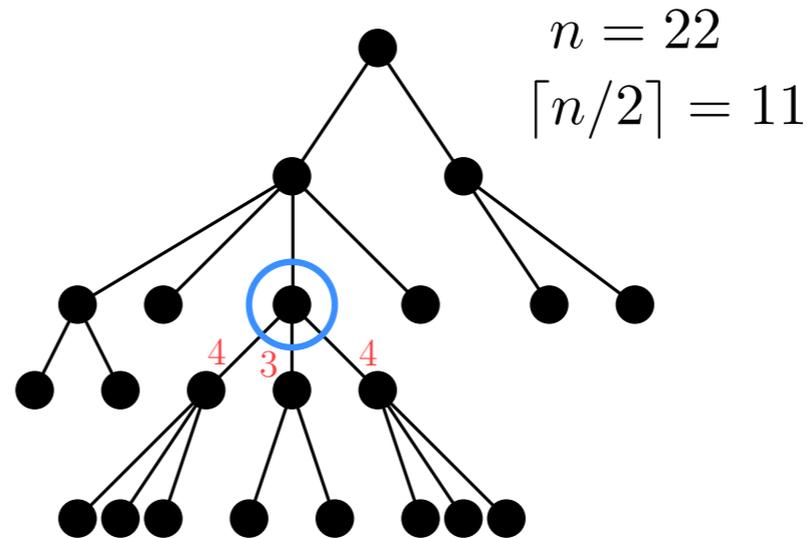


Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.

Claim: Any tree T **always** contains a separator.

Walk through the tree starting at root, going into the subtree that contains $\geq \lceil n/2 \rceil$ nodes.

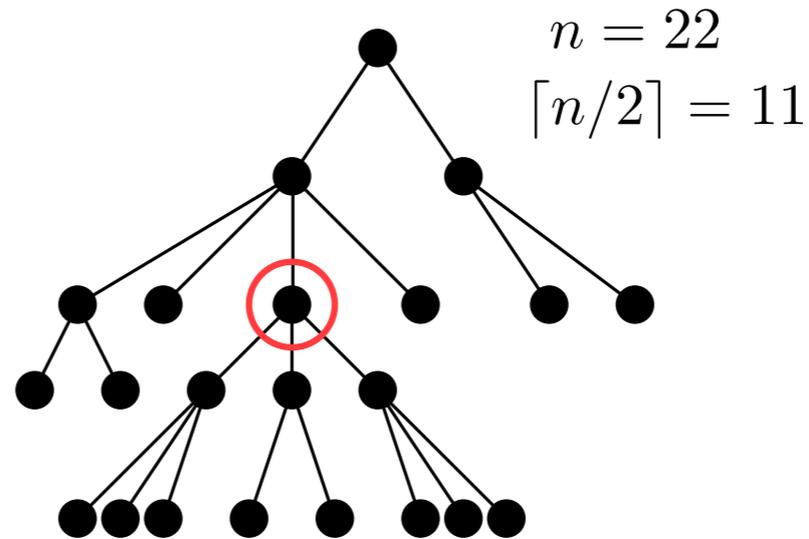


Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.

Claim: Any tree T **always** contains a separator.

Walk through the tree starting at root, going into the subtree that contains $\geq \lceil n/2 \rceil$ nodes.



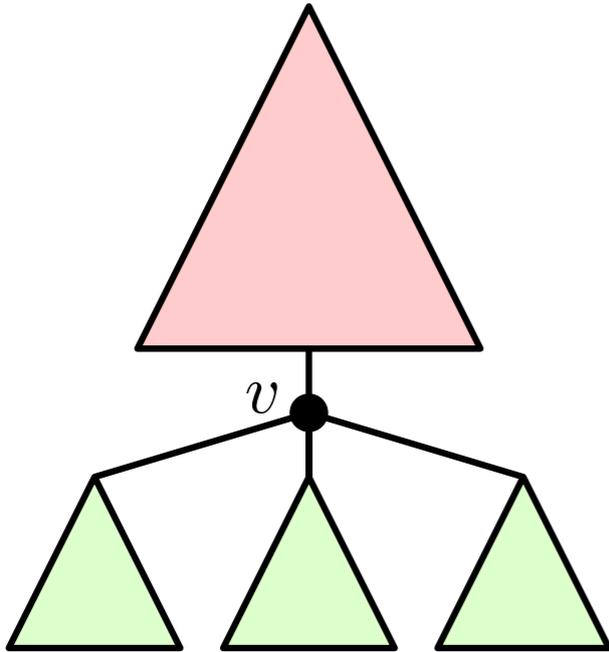
Once we get stuck:

- child subtree sizes $< \lceil n/2 \rceil$
- rooted subtree size $\leq n - \lceil n/2 \rceil \leq \lfloor n/2 \rfloor$

Fast point-location - Fingering the quadtree

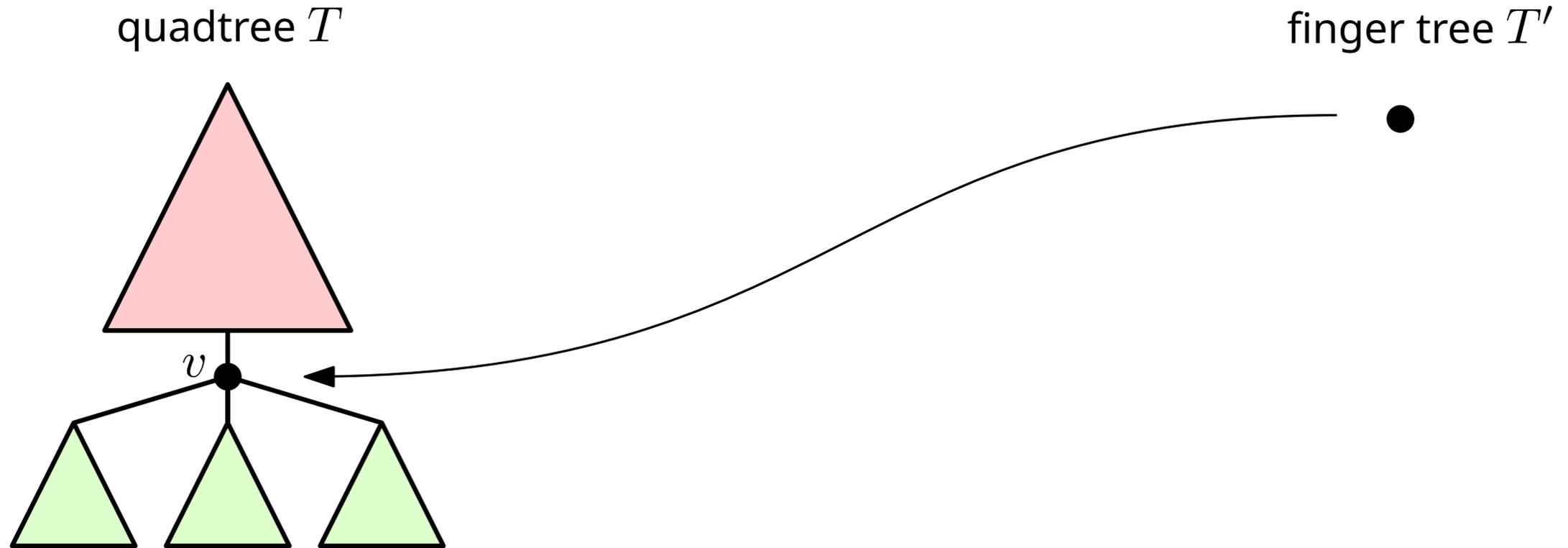
Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.

quadtree T



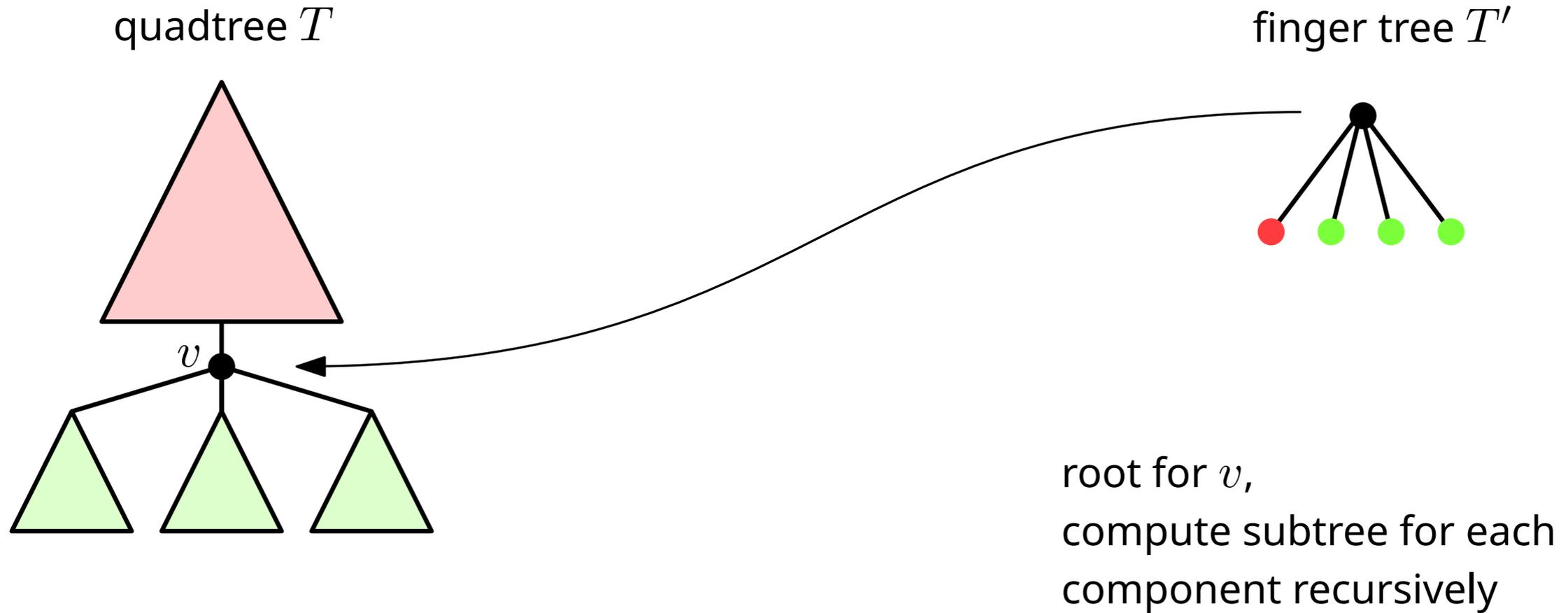
Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.



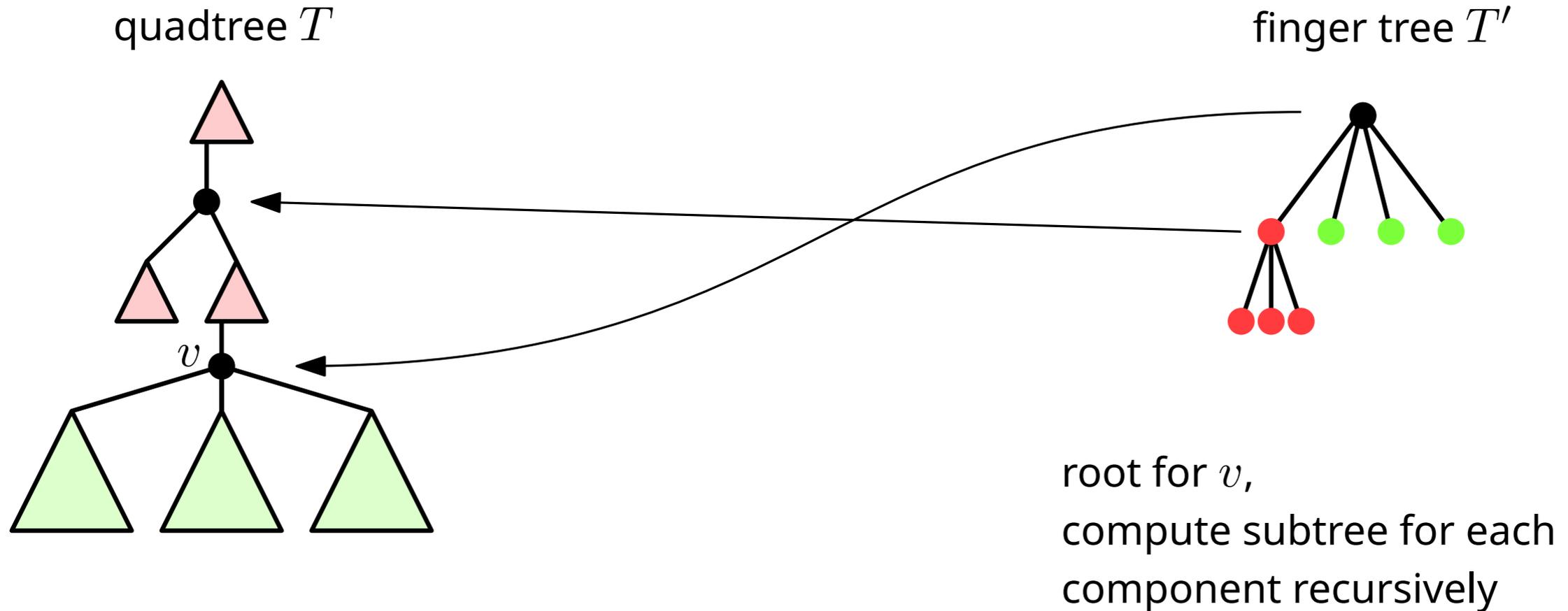
Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.



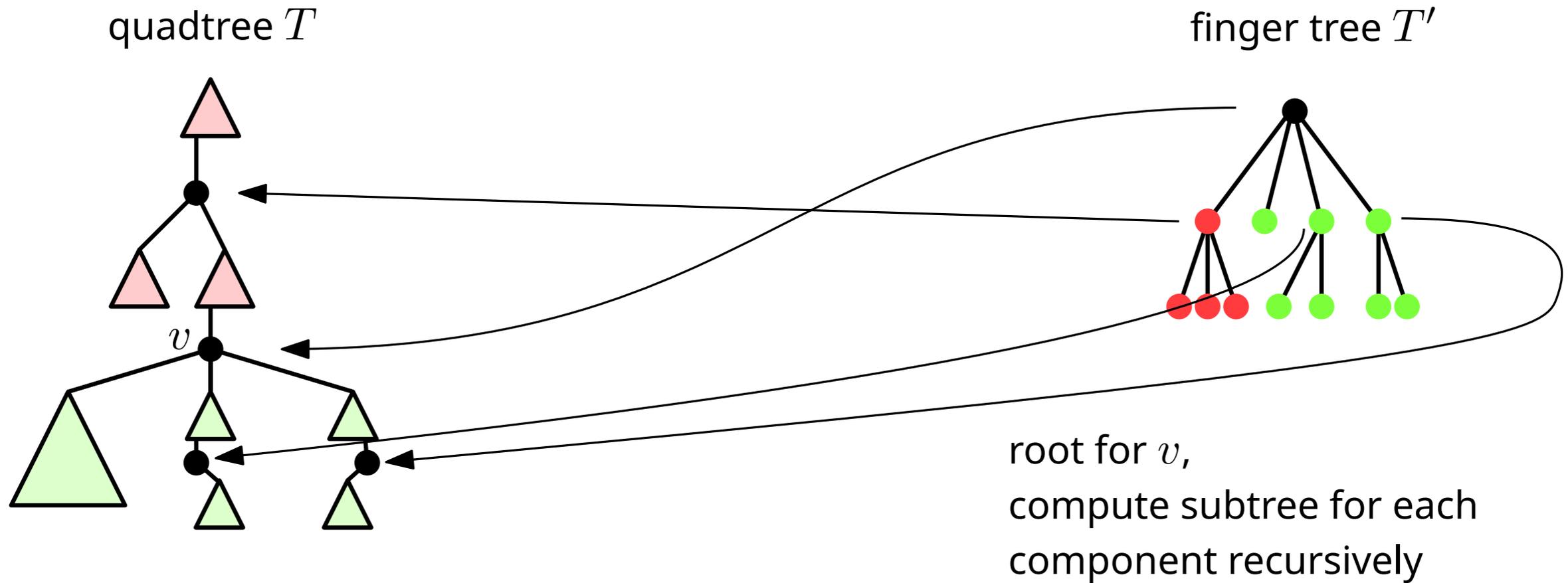
Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.



Fast point-location - Fingering the quadtree

Definition: A **separator** of a tree T with n nodes is a node $v \in T$ such that removing v results in a forest of which every tree has at most $\lceil n/2 \rceil$ nodes.



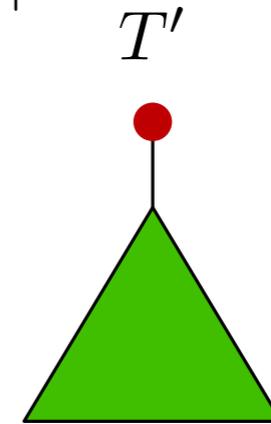
What are the **height/query time** and the **construction time** of the finger tree?

Finger trees

Recall that the [separator](#) splits T into subtrees of size $\leq \lceil n/2 \rceil$

recurrence for [height](#):

$$\implies H(n) \leq 1 + H(\lceil n/2 \rceil) = O(\log n)$$

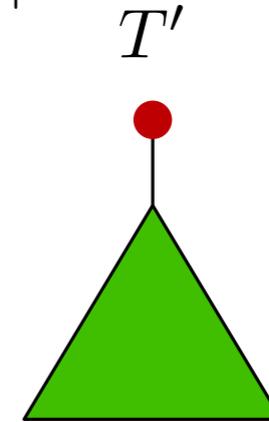


Finger trees

Recall that the **separator** splits T into subtrees of size $\leq \lceil n/2 \rceil$

recurrence for **height**:

$$\implies H(n) \leq 1 + H(\lceil n/2 \rceil) = O(\log n)$$

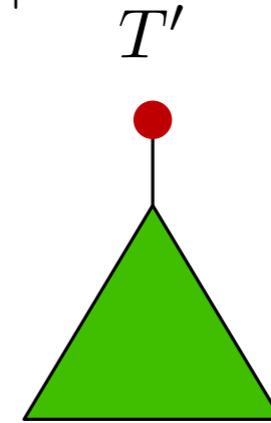


Finger trees

Recall that the **separator** splits T into subtrees of size $\leq \lceil n/2 \rceil$

recurrence for **height**:

$$\implies H(n) \leq 1 + H(\lceil n/2 \rceil) = O(\log n)$$

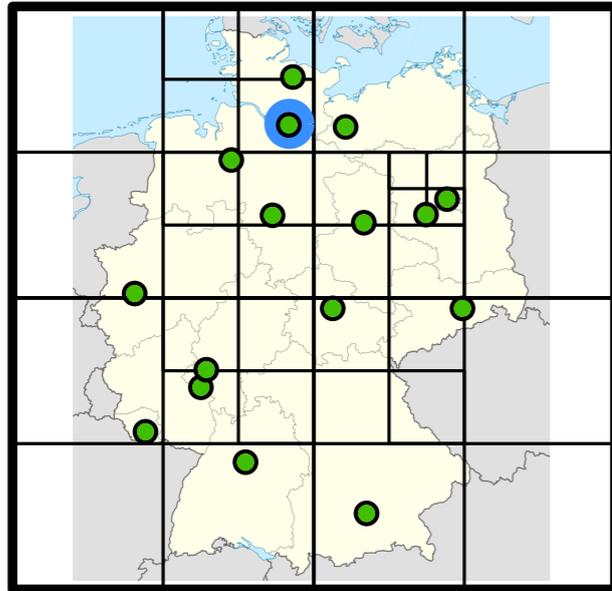


Construction time $T(n) = O(n) + \sum_{i=1}^t T(n_i)$ where $n_1 \dots n_t$ are the sizes of the t subtrees formed after removing the separator.

Since $t = O(1)$ and $n_i \leq \lceil n/2 \rceil$, we have $T(n) = O(n \log n)$

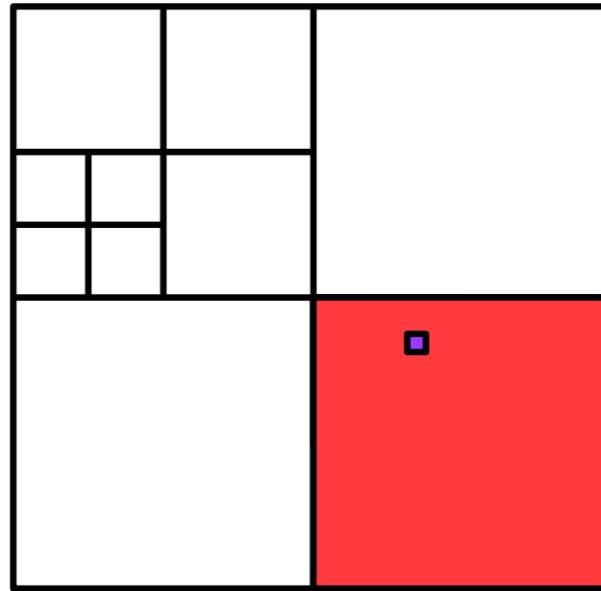
Summary

Normal quadtrees



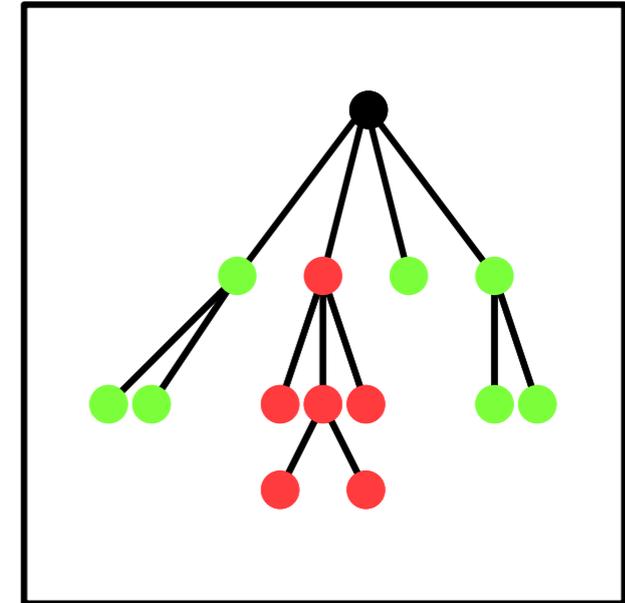
Bounded by spread

Compressed quadtrees



Bounded by number of points

Finger trees



Fast query time

more in book: [dynamic](#) quadtrees